

Topic-Based Communication Between Agents*

Rustam Galimullin and Fernando R. Velázquez-Quesada

Department of Information Science and Media Studies, University of Bergen
{Rustam.Galimullin, Fernando.VelazquezQuesada}@uib.no

Abstract

Communication within groups of agents has been lately the focus of research in dynamic epistemic logic (DEL). This paper studies a recently introduced form of *partial* (more precisely, *topic-based*) *communication*. This type of communication allows for modelling scenarios of multi-agent collaboration and negotiation, and it is particularly well-suited for situations in which sharing all information is not feasible/advisable. The paper can be divided into two parts. In the first part, we present results on invariance and complexity of model checking. Moreover, we compare partial communication with the public announcement and arrow update settings in terms of both language-expressivity and update-expressivity. Regarding the former, the three settings are equivalent, their languages being equally expressive. Regarding the latter, all three modes of communication are incomparable in terms of update-expressivity. In the second part, we shift our attention to *strategic* topic-based communication. We do so by extending the language with a modality that quantifies over the topics the agents can ‘talk about’, thus allowing a form of *arbitrary partial communication*. For this new framework, we provide a complete axiomatisation, showing also that the new language’s model checking problem is *PSPACE*-complete. Finally, we argue that, in terms of expressivity, this new language of arbitrary partial communication is incomparable to that of arbitrary public announcements and also to that of arbitrary arrow updates.

Keywords: Epistemic Logic · Distributed Knowledge · Dynamic Epistemic Logic · Partial Communication · Public Announcements · Arrow Updates · Arbitrary Partial Communication · Arbitrary Public Announcements · Arbitrary Arrow Updates

1 Introduction

Epistemic logic (*EL*; Hintikka 1962) is a powerful framework for representing knowledge/beliefs of both individual agents and groups thereof. When using relational ‘Kripke’ models, its crucial idea is the use of uncertainty for defining knowledge. Indeed, such structures assign to each agent a binary relation

*Extended and revised version of Galimullin and Velázquez-Quesada 2023.

37 indicating *indistinguishability* among epistemic possibilities. Then, it is said
 38 that an agent i knows that φ is the case (syntactically: $K_i \varphi$) when φ holds
 39 in all situations i considers possible. Despite its simplicity, *EL* has become
 40 a widespread tool, contributing to the formal study of complex multi-agent
 41 epistemic phenomena in philosophy (Hendricks 2006), computer science (Fagin
 42 et al. 1995), AI (Meyer and van der Hoek 1995) and economics (de Bruin 2010).

43 One of the most appealing aspects of *EL* is that it can be used to reason about
 44 information change. This has been the main subject of dynamic epistemic logic
 45 (*DEL*; van Ditmarsch et al. 2008, van Benthem 2011), a field whose main fea-
 46 ture is that actions are semantically represented as operations that transform
 47 the underlying semantic model.¹ Within *DEL*, one of the simplest meaningful
 48 epistemic actions is that of a *public announcement*: an external source providing
 49 the agents with truthful information in a fully public way (Plaza 1989, Ger-
 50 brandy and Groeneveld 1997). Yet, the agents do not need to wait for some
 51 external entity to feed them with facts: they can also share their individual
 52 information with one another. This is arguably a more suitable way of model-
 53 ling information change in multi-agent (and, in particular, distributed) systems.
 54 Agents might occasionally receive information ‘from the outside’, but the most
 55 common form of interaction is the one in which they themselves engage in
 56 ‘conversations’ to share what they have obtained so far. It is this form of in-
 57 formation exchange that allows independent entities to engage in collaboration,
 58 negotiation, and so on.

59 Agent communication can take several forms, and some variations have
 60 been explored within the *DEL* framework. A single agent might share all
 61 her information with everybody, as modelled in Baltag (2010). Alternatively,
 62 a group of agents might share all their information only among themselves,
 63 as represented by the action of “resolving distributed knowledge” studied in
 64 Ågotnes and Wáng (2017). One can even think about this form of communica-
 65 tion not as a form of ‘sharing’, but rather as a form of ‘taking’ (Baltag and Smets
 66 2020, 2021), which allows the study of public and private forms of reading
 67 someone else’s information (e.g., hacking).

68 All these approaches for communication have a common feature: when
 69 sharing/taking, the agents share/take *all the available information*. This is of
 70 course useful, as then one can reason about the best the agents can do together.
 71 But there are also scenarios (arguably more common) in which sharing all her
 72 available information might not be feasible or advisable for an agent. For the
 73 first, there might be constraints on the communication channels; for the second,
 74 agents might not be in a cooperative scenario, but rather in a competitive
 75 one. In such cases, one would be rather interested in studying forms of *partial*
 76 communication, through which agents share only ‘part of what they know’.
 77 There might be different ways to make precise what each agent shares, but a
 78 natural one is to assume that the ‘conversation’ is relative to a subject/topic,
 79 defined by a given formula χ . Introduced in Velázquez-Quesada (2022), this
 80 type of communication allows for more realistic modelling of scenarios of
 81 multi-agent collaboration and negotiation.

82 This paper studies different aspects of this partial communication setting.

¹This is different, e.g., from *dynamic logic* (Harel et al. 2000), where actions are represented as relations.

It starts (Section 2) by recalling the underlying framework (*EL* with distributed knowledge). Then, it presents the basics of the *partial communication* framework (Section 3), providing definitions (language, semantic interpretation) and results (axiom system, structural equivalence, expressivity and complexity of model checking) as well as comparing it with two well-known *DEL* frameworks, namely public announcements and arrow updates. The comparison shows interesting connections. First, the languages of the three systems are equally expressive.² Then, their ‘update expressivity’ is different. On the one hand, in general, the partial communication and public announcement operations cannot mimic each other: there are scenarios in which, from the language’s point of view, the effect of a public announcement cannot be replicated by partial communication, and vice versa. On the other hand, partial communication and arrow updates cannot in general mimic each other either.

Still, in truly competitive scenarios, what matters the most is not the effects of what is being shared, but rather the decision of *what* to share. In other words, what matters is being able to reason about *strategic* topic-based communication. To do so, this paper introduces (Section 4) a logical framework for quantifying over the conversation’s topic, thus allowing *arbitrary partial communication*. It presents the basic definitions, providing then results on invariance, axiom system, expressivity and the complexity of its model checking problem. After that, it compares this new setting with that of arbitrary public announcements and that of arbitrary arrow updates. In both cases, it is shown that the languages are, expressivity-wise, incomparable. The paper closes (Section 5) summarising the paper’s contents while also discussing further research lines.

2 Background

Models and relative expressivity. Throughout this text, let \mathbf{A} be a finite non-empty group of agents, and let \mathbf{P} be a non-empty enumerable set of atomic propositions.

Definition 2.1 (Model) A *multi-agent relational model* (from now on, a model) is a tuple $M = \langle W, R, V \rangle$ where W (also denoted as $\mathfrak{D}(M)$) is a non-empty set of objects called *possible worlds*, $R = \{R_i \subseteq W \times W \mid i \in \mathbf{A}\}$ assigns a binary “indistinguishability” relation on W to each agent in \mathbf{A} (for $G \subseteq \mathbf{A}$, define $R_G := \bigcap_{k \in G} R_k$), and $V : \mathbf{P} \rightarrow \wp(W)$ is an atomic valuation (with $V(p)$ being the set of worlds in M where $p \in \mathbf{P}$ holds). A pair (M, w) , where M is a model and $w \in \mathfrak{D}(M)$, is a *pointed model*, with w being the *evaluation point*. A model M is *finite* if and only if both W and $\bigcup_{w \in W} \{p \in \mathbf{P} \mid w \in V(p)\}$ are finite. If $M = \langle W, R, V \rangle$ is finite, its *size* (notation: $|M|$) is given by $|W| + \sum_{i \in \mathbf{A}} |R_i| + \sum_{w \in W} |\{p \in \mathbf{P} \mid w \in V(p)\}|$. ◀

In a model, the agents’ indistinguishability relations are arbitrary. In particular, they need to be neither reflexive nor symmetric nor Euclidean nor transitive. There are two reasons for this. On the conceptual side, although equivalence relations are somehow standard for representing the notion of knowledge, several authors have argued against positive and negative introspection, epistemic properties directly connected to the relational properties of

²This holds assuming that their epistemic fragment contains the distributed knowledge modality.

transitivity and Euclidicity. Indeed, it has been argued that both forms of introspection are, in many situations, unreachable idealisations that might lead to contradictory situations (see, e.g., [Lemmon 1967](#), [Danto 1967](#), [Williamson 2002](#) for positive introspection, and [Hintikka 1962](#) for negative introspection; see also the discussion in the introduction of [Fervari and Velázquez-Quesada 2019](#)). On the technical side, the partial communication operation ([Definition 3.1](#) below) preserves reflexivity but neither transitivity nor Euclidicity. Thus, requiring the two latter properties would have made the operation ‘non-suitable’, as it would change the class of models.³ If needed, asking for the relations to be reflexive is (both conceptually and technically) a safe choice. This paper takes rather a more general perspective, working with arbitrary relations. Because of this, “knowledge” here is neither truthful nor positively/negatively introspective. It rather corresponds, simply, to “what is true in all the agent’s (agents’) epistemic alternatives”.

Definition 2.2 (Relative expressivity) Let \mathcal{L}_1 and \mathcal{L}_2 be two languages interpreted over pointed models. It is said that \mathcal{L}_2 is at least as expressive as \mathcal{L}_1 (notation: $\mathcal{L}_1 \leq \mathcal{L}_2$) if and only if for every $\phi_1 \in \mathcal{L}_1$ there is $\phi_2 \in \mathcal{L}_2$ such that ϕ_1 and ϕ_2 have the same truth-value in every pointed model (i.e., $(M, w) \models \phi_1$ if and only if $(M, w) \models \phi_2$ for every M and every $w \in \mathfrak{D}(M)$). Write $\mathcal{L}_1 \approx \mathcal{L}_2$ when $\mathcal{L}_1 \leq \mathcal{L}_2$ and $\mathcal{L}_2 \leq \mathcal{L}_1$; write $\mathcal{L}_1 < \mathcal{L}_2$ when $\mathcal{L}_1 \leq \mathcal{L}_2$ and $\mathcal{L}_2 \not\leq \mathcal{L}_1$; write $\mathcal{L}_1 \asymp \mathcal{L}_2$ when $\mathcal{L}_1 \not\leq \mathcal{L}_2$ and $\mathcal{L}_2 \not\leq \mathcal{L}_1$. ◀

Note: for proving $\mathcal{L}_1 \not\leq \mathcal{L}_2$, it is enough to find two (classes of) pointed models that agree on all formulas in \mathcal{L}_2 but can be distinguished by a formula in \mathcal{L}_1 . Indeed, let (N, u) and (N', u') be the pointed models indistinguishable by \mathcal{L}_2 and let $\phi_1 \in \mathcal{L}_1$ be a formula that distinguishes them. For a contradiction, suppose $\mathcal{L}_1 \leq \mathcal{L}_2$. Then, there would be a formula $\phi_2 \in \mathcal{L}_2$ agreeing with ϕ_1 in every pointed model; in particular, they would agree in both (N, u) and (N', u') . But (N, u) and (N', u') cannot be distinguished by \mathcal{L}_2 , so ϕ_2 has the same truth value in both pointed models. Then, so does ϕ_1 , contradicting the fact that it can distinguish them.

Syntax and semantics. Here is this paper’s basic language for describing pointed models.

Definition 2.3 (Language \mathcal{L}) Formulas φ, ψ in \mathcal{L} are given by

$$\varphi, \psi ::= p \mid \neg\varphi \mid (\varphi \wedge \psi) \mid D_G \varphi$$

for $p \in \mathbf{P}$ and $\emptyset \subset G \subseteq \mathbf{A}$. Boolean constants and other Boolean operators are defined as usual. We will also omit parentheses whenever it does not impede clarity. Define also $K_i \varphi := D_{\{i\}} \varphi$ and $\widehat{K}_i \varphi := \neg K_i \neg\varphi$. The set of atoms in a formula is defined recursively as usual:

$$\text{at}(p) := \{p\}, \quad \text{at}(\neg\varphi) := \text{at}(\varphi), \quad \text{at}(\varphi \wedge \psi) := \text{at}(\varphi) \cup \text{at}(\psi), \quad \text{at}(D_G \varphi) := \text{at}(\varphi).$$

Finally, the size of φ , denoted as $|\varphi|$, is defined recursively in the standard way:

$$|p| := 1, \quad |\neg\varphi| := |\varphi| + 1, \quad |\varphi \wedge \psi| := |\varphi| + |\psi| + 1, \quad |D_G \varphi| := |\varphi| + 1. \quad \blacktriangleleft$$

³Moreover, rule RE_{S_X} in [Table 2](#) would not preserve validity.

165 The language \mathcal{L} contains a modality D_G for each non-empty group of agents
 166 $G \subseteq A$. Formulas of the form $D_G \varphi$ are read as “the agents in G know φ dis-
 167 tributively”; thus, $K_i \varphi$ is read as “ i knows φ distributively”, i.e., “agent i
 168 knows φ ”.

169 The use of the modality for distributed knowledge (Halpern 1977, Halpern
 170 and Moses 1984, 1985, 1990) might require further justification. Intuitively, φ is
 171 distributed knowledge among a group of agents if and only if it follows from the
 172 combination of the individual knowledge of the group’s members (or, in other
 173 words, if the agents *would* know φ by putting all their information together).
 174 Distributed knowledge thus ‘pre-encodes’ what a group of agents would know
 175 if they were to share their individual information among themselves. Because
 176 of this, it will be a very useful tool in this text.

177 Now, in models that represent directly the individual knowledge of the
 178 agents, distributed knowledge has a straightforward definition: put the know-
 179 ledge of the members of the group together (using the union operation), and
 180 then get the closure under logical consequence. In relational models, which
 181 represent rather the agent’s uncertainty, there is also a natural way of defining
 182 a relation for the agents’ distributed knowledge: given a world w , the group
 183 G will consider u as possible if and only if, given w , everybody in G considers
 184 u possible (or, equivalently, *no one* in G can rule u out). In other words, the
 185 indistinguishability relation for the distributed knowledge of a group is the
 186 intersection of the indistinguishability relations of the group’s members. With
 187 this, the language’s semantic interpretation is as follows.

188 **Definition 2.4 (Semantic interpretation for \mathcal{L})** Let (M, w) be a pointed model
 189 with $M = \langle W, R, V \rangle$. The satisfiability relation \models between (M, w) and formulas
 190 in \mathcal{L} is defined inductively.

$$\begin{aligned}
 (M, w) \models p & \quad \text{iff}_{\text{def}} \quad w \in V(p), \\
 (M, w) \models \neg \varphi & \quad \text{iff}_{\text{def}} \quad (M, w) \not\models \varphi, \\
 (M, w) \models \varphi \wedge \psi & \quad \text{iff}_{\text{def}} \quad (M, w) \models \varphi \text{ and } (M, w) \models \psi, \\
 (M, w) \models D_G \varphi & \quad \text{iff}_{\text{def}} \quad \text{for all } u \in W, \text{ if } R_G w u \text{ then } (M, u) \models \varphi.
 \end{aligned}$$

192 Given a model M and a formula φ ,

- 193 • the set $\llbracket \varphi \rrbracket^M := \{w \in \mathfrak{D}(M) \mid (M, w) \models \varphi\}$ contains the worlds in $\mathfrak{D}(M)$ in
 194 which φ holds (also called φ -worlds);
- the (note: equivalence) relation

$$\sim_\varphi^M := (\llbracket \varphi \rrbracket^M \times \llbracket \varphi \rrbracket^M) \cup (\llbracket \neg \varphi \rrbracket^M \times \llbracket \neg \varphi \rrbracket^M)$$

195 splits $\mathfrak{D}(M)$ into (up to) two equivalence classes: one containing all φ -
 196 worlds, and the other containing all $\neg \varphi$ -worlds.

197 A formula φ is valid (notation: $\models \varphi$) if and only if $(M, w) \models \varphi$ for every $w \in \mathfrak{D}(M)$
 198 of every model M . ◀

199 **Axiom system.** The axiom system L (Table 1; Halpern and Moses 1990, Fagin
 200 et al. 1992) characterises the valid formulas in \mathcal{L} . The behaviour of Boolean
 201 operators is taken care of by PR and MP. For the modality D_G , while rule
 202 G_D indicates that it ‘contains’ all validities, axiom K_D indicates that it is closed

PR: $\vdash \varphi$ for φ a propositionally valid scheme
MP: If $\vdash \varphi$ and $\vdash \varphi \rightarrow \psi$ then $\vdash \psi$
$K_D: \vdash D_G(\varphi \rightarrow \psi) \rightarrow (D_G \varphi \rightarrow D_G \psi)$ $G_D: \text{If } \vdash \varphi \text{ then } \vdash D_G \varphi$
$M_D: \vdash D_G \varphi \rightarrow D_{G'} \varphi$ for $G \subseteq G'$

Table 1: Axiom system L.

under modus ponens, and axiom M_D states that it is monotone on the group of agents (if φ is distributively known by G , then it is also distributively known by any larger group G').

Theorem 1 *The axiom system L (Table 1) is sound and strongly complete for \mathcal{L} w.r.t. the given class of models.* ■

Structural equivalence. When discussing the expressivity of a language, it is useful to have a semantic notion that connects two pointed models when they cannot be distinguished by the language's formulas. For the basic modal language (Boolean operators plus modalities for the individual relations), the notion of bisimulation plays this role (see, e.g., Blackburn et al. 2001, Definition 2.18 and Theorem 2.20). When the modality for distributed knowledge is included, one needs rather the notion of *collective* bisimulation (Roelofsen 2007), which expands on a standard bisimulation by asking for the **forth** and **back** clauses to be satisfied not only by all singletons $\{i\} \subseteq A$ but also by all groups of agents $G \subseteq A$. The definition provided below makes a further generalisation, making the relevant set of atoms a parameter. This will be useful for discussing the expressivity of languages that quantify over information change (Section 4).

Definition 2.5 (Collective Q-bisimulation) Let $Q \subseteq P$ be a set of atoms; let $M = \langle W, R, V \rangle$ and $M' = \langle W', R', V' \rangle$ be two models. A non-empty relation $Z \subseteq W \times W'$ is a *collective Q-bisimulation between M and M'* if and only if every $(u, u') \in Z$ satisfies the following.

- **Atoms.** For every $p \in Q$: $u \in V(p)$ if and only if $u' \in V'(p)$.
- **Forth.** For every $G \subseteq A$ and every $v \in W$: if $R_G uv$ then there is $v' \in W'$ such that both $R'_G u'v'$ and $(v, v') \in Z$.
- **Back.** For every $G \subseteq A$ and every $v' \in W'$: if $R'_G u'v'$ then there is $v \in W$ such that both $R_G uv$ and $(v, v') \in Z$.

Write $M \rightleftharpoons_C^Q M'$ if and only if there is a collective Q-bisimulation between M and M' . Write $(M, w) \rightleftharpoons_C^Q (M', w')$ if and only if a witness for $M \rightleftharpoons_C^Q M'$ contains the pair (w, w') . If Q is the full set of atoms P , it will be omitted from the notation. ◀

Note that the relation of collective Q-bisimilarity is an equivalence relation, both on models and pointed models.⁴

The following proposition shows that a collective bisimulation is useful for our purposes: the language \mathcal{L} is invariant under collective bisimilarity.

⁴Indeed, take arbitrary pointed models (M, w) , (M', w') and (M'', w'') . Then, (i) the identity relation on W is a witness for both $M \rightleftharpoons_C^Q M$ and $(M, w) \rightleftharpoons_C^Q (M, w)$; (ii) if $Z \subseteq W \times W'$ is a witness for $M \rightleftharpoons_C^Q M'$ (resp., $(M, w) \rightleftharpoons_C^Q (M', w')$), then $Z^{-1} \subseteq W' \times W$ is a witness for $M' \rightleftharpoons_C^Q M$ (resp.,

236 **Theorem 2 (\rightleftharpoons_C implies \mathcal{L} -equivalence)** Let (M, w) and (M', w') be two pointed
 237 models; take $Q \subseteq P$. If $(M, w) \rightleftharpoons_C^Q (M', w')$ then, for every $\psi \in \mathcal{L}$ with $\text{at}(\psi) \subseteq Q$,

$$238 \quad (M, w) \models \psi \quad \text{if and only if} \quad (M', w') \models \psi.$$

239 *Proof.* Proofs showing that a form of structural equivalence implies invariance
 240 for a language usually proceed by structural induction on the language's for-
 241 mulas.⁵ For the case of collective bisimilarity and \mathcal{L} , see Roelofsen (2007). ■

242 **Model checking** The complexity of the model checking problem for \mathcal{L} (given
 243 a pointed model and a formula in \mathcal{L} , decide whether the formula is true at the
 244 pointed model) is in P Fagin et al. (1995, Page 67).

245 3 Partial communication

246 The intuition behind the action of partial communication is that, through it,
 247 a group of agents $S \subseteq A$ share, with everybody, all their information about a
 248 given topic χ . Before looking at its formal definition, it is useful to consider the
 249 definition of a simpler action: one through which the agents in S share *all their*
 250 *information* with everybody.⁶

251 After agents in S share all their information with everybody, a given agent i
 252 at a world w will consider a world u possible if and only if neither her nor any
 253 agent in S could rule out u from w before the action. In other words, after this
 254 full communication action, an agent i will consider a world u possible from a
 255 world w if and only if she and every agent in S already considered u possible
 256 from w . This means that, after the action, i 's indistinguishability relation is
 257 the *intersection* of the relations R_i and R_S : edges that are not labelled by all
 258 communicating agents will be removed.

259 Now, suppose the agents in S share only 'their information about χ ' (intuit-
 260 ively, only what has allowed them to distinguish between χ - and $\neg\chi$ -worlds).
 261 In such case, as argued in Velázquez-Quesada (2022), edges between worlds
 262 agreeing in χ 's truth-value are not 'part of the discussion', and thus they should
 263 not be eliminated. In other words, only edges connecting worlds disagreeing
 264 in χ 's truth-value can be eliminated, and they will be eliminated if and only if
 265 they are not labelled by all communicating agents.

266 3.1 Syntax, semantics, and model checking

267 **Definition 3.1 (Partial communication)** Let $M = \langle W, R, V \rangle$ be a model; take a
 268 group of agents $S \subseteq A$ and a formula χ . The model $M_{S:\chi} = \langle W, R^{S:\chi}, V \rangle$, the
 269 result of agents in S sharing all they know about χ with everybody, is such that

$(M', w') \rightleftharpoons_C^Q (M, w)$; (iii) if $Z_1 \subseteq W \times W'$ and $Z_2 \subseteq W' \times W''$ are witnesses for $M \rightleftharpoons_C^Q M'$ and
 $M' \rightleftharpoons_C^Q M''$ (resp., $(M, w) \rightleftharpoons_C^Q (M', w')$ and $(M', w') \rightleftharpoons_C^Q (M'', w'')$), then $Z_2 \circ Z_1$ is a witness for
 $M \rightleftharpoons_C^Q M''$ (resp., $(M, w) \rightleftharpoons_C^Q (M'', w'')$).

⁵The proofs typically start by pulling out the universal quantifier over formulas. This way,
 the statement becomes "for every ψ (containing only atoms from Q), any structurally equivalent pointed
 models agree on ψ 's truth-value". This yields a stronger inductive hypothesis (IH) thanks to which
 the proof can go through. This will be done throughout the rest of the text.

⁶Cf. the resolving action of Ágotnes and Wáng (2017), through which a group of agents share all
 their information *within themselves*.

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$$R^{S:\chi}_i := R_i \cap (R_S \cup \sim^M_\chi).$$

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A couple of observations are useful.

- First, the indistinguishability relation for the *distributed knowledge* of a group of agents G in the new model (i.e., the intersection of the new indistinguishability relations), denoted as $R^{S:\chi}_G$, can be written in a slightly simplified way:

$$R^{S:\chi}_G = \bigcap_{i \in G} R^{S:\chi}_i = \bigcap_{i \in G} (R_i \cap (R_S \cup \sim^M_\chi)) = R_G \cap (R_S \cup \sim^M_\chi) = R_{G \cup S} \cup (R_G \cap \sim^M_\chi).$$

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- Second: $R^{\emptyset:\chi}_i = R_i$. Thus, if the set of communicating agents S is empty, indistinguishability (and hence knowledge) remains the same.

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On the syntactic side, the following modality is useful for describing the effects of the action of partial communication.

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Definition 3.2 (Modality $[S:\chi]$ and language \mathcal{L}_{PC}) Define $\mathcal{L}_{PC}[0] := \mathcal{L}$, where PC stands for *partial communication*. Then, define $\mathcal{L}_{PC}[i+1]$ as the result of extending $\mathcal{L}_{PC}[i]$ with an additional modality $[S:\chi]$ for $S \subseteq \mathbf{A}$ and $\chi \in \mathcal{L}_{PC}[i]$. The language \mathcal{L}_{PC} is the union of all $\mathcal{L}_{PC}[n]$ with $n \in \mathbb{N}$, thus essentially extending \mathcal{L} with a modality $[S:\chi]$ for each $S \subseteq \mathbf{A}$ and each formula χ . The set of atoms and size for formulas in \mathcal{L}_{PC} is as in [Definition 2.3](#) with the additional clauses $\text{at}([S:\chi]\varphi) := \text{at}(\chi) \cup \text{at}(\varphi)$ and $\| [S:\chi]\varphi \| := |\chi| + |\varphi| + 1$, respectively. For the semantic interpretation,

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$$(M, w) \models [S:\chi]\varphi \quad \text{iff}_{def} \quad (M_{S:\chi}, w) \models \varphi.$$

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Define $\langle S:\chi \rangle \varphi := \neg [S:\chi] \neg \varphi$. Note how this implies $\models \langle S:\chi \rangle \varphi \leftrightarrow [S:\chi] \varphi$. ◀

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Further motivation and details on the partial communication setting can be found in [Velázquez-Quesada \(2022\)](#). Still, here are two properties that help to understand what the action does.

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- If $\models \chi_1 \leftrightarrow \chi_2$ then $\models [S:\chi_1]\varphi \leftrightarrow [S:\chi_2]\varphi$: logically equivalent topics have the same communication effect.

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- $\models [S:\chi]\varphi \leftrightarrow [S:\neg\chi]\varphi$: communication on a topic is just as communication on its negation.

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Finally, note that partial communication is *not* a generalisation of an action through which some agents share *all* their information. For this to be the case, the “some agents share all” action should be a particular instance of the partial communication setting, and this is not the case: there is no formula χ such that, in every possible situation, communication about χ is equivalent to communication about all topics.

Axiom system. The axioms and rule of [Table 2](#) form, together with those in [Table 1](#), a sound and strongly complete axiom system for \mathcal{L}_{PC} . They rely on the *DEL* reduction axioms technique (for an explanation, see [Wang and Cao 2013](#) or [van Ditmarsch et al. 2008](#), Section 7.4), which, in turn, crucially relies on the existence of a (recursively defined) truth-preserving translation from \mathcal{L}_{PC} to \mathcal{L} . In the translation, axiom $A_{S:\chi}^D$ is the central one, as it characterises

$A_{S;\chi}^p$	$\vdash [S:\chi]p \leftrightarrow p$
$A_{S;\chi}^-$	$\vdash [S:\chi]\neg\varphi \leftrightarrow \neg[S:\chi]\varphi$
$A_{S;\chi}^\wedge$	$\vdash [S:\chi](\varphi \wedge \psi) \leftrightarrow ([S:\chi]\varphi \wedge [S:\chi]\psi)$
$A_{S;\chi}^D$	$\vdash [S:\chi]D_G\varphi \leftrightarrow (D_{S \cup G}[S:\chi]\varphi \wedge D_G^x[S:\chi]\varphi)$
$RE_{S;\chi}$	If $\vdash \varphi_1 \leftrightarrow \varphi_2$ then $\vdash [S:\chi]\varphi_1 \leftrightarrow [S:\chi]\varphi_2$

Table 2: Additional axioms and rules for $L_{S;\chi}$.

distributed knowledge after the operation in terms of distributed knowledge about the effects of the operation. Using the abbreviation

$$D_G^x\varphi := (\chi \rightarrow D_G(\chi \rightarrow \varphi)) \wedge (\neg\chi \rightarrow D_G(\neg\chi \rightarrow \varphi))$$

(“agents in G know distributively that χ ’s truth value, regardless of what it is, implies φ ”),

the axiom indicates that a group G knows φ distributively after the action $([S:\chi]D_G\varphi)$ if and only if the group $S \cup G$ knew, distributively, that φ would hold after the action $(D_{S \cup G}[S:\chi]\varphi)$ and the agents in G know distributively that χ ’s truth-value, regardless of what it is, implies that the action will make φ true $(D_G^x[S:\chi]\varphi)$.

From these axioms and rule (Table 2) together with their induced translation (see Velázquez-Quesada 2022 for details), the following theorem follows.

Theorem 3 *The axiom system $L_{S;\chi}$ (Table 1+Table 2) is sound and strongly complete for \mathcal{L}_{PC} .*

So far this section has recalled basic definitions and results from the partial communication setting. The following results on structural equivalence, expressivity and complexity, are new.

Structural equivalence. As it turns out, the partial communication modality $[S:\chi]$ (and thus, from Theorem 2, the full language \mathcal{L}_{PC}) is invariant under collective bisimilarity.

Theorem 4 (\rightleftharpoons_C implies \mathcal{L}_{PC} -equivalence) *Let (M, w) and (M', w') be two pointed models; take $Q \subseteq P$. If $(M, w) \rightleftharpoons_C^Q (M', w')$ then, for every $\psi \in \mathcal{L}_{PC}$ with $\text{at}(\psi) \subseteq Q$,*

$$(M, w) \models \psi \quad \text{if and only if} \quad (M', w') \models \psi.$$

Proof. The language \mathcal{L}_{PC} is the union of $\mathcal{L}_{PC}[n]$ for all $n \in \mathbb{N}$, so the proof proceeds by induction on n . In fact, the text proves a stronger statement: for every $\psi \in \mathcal{L}_{PC}$ with $\text{at}(\psi) \subseteq Q$ and every (M, w) and (M', w') , if $(M, w) \rightleftharpoons_C^Q (M', w')$ then (1) $(M, w) \models \psi$ if and only if $(M', w') \models \psi$, and (2) $(M_{S:\psi}, w) \rightleftharpoons_C^Q (M'_{S:\psi}, w')$. Details can be found in the appendix. ■

Expressivity. It is clear that $\mathcal{L} \leq \mathcal{L}_{PC}$, as every formula in the former is also in the latter. Moreover: the reduction axioms in Table 2 define a (recursive) translation $tr : \mathcal{L}_{PC} \rightarrow \mathcal{L}$ such that $\varphi \in \mathcal{L}_{PC}$ implies $\models \varphi \leftrightarrow tr(\varphi)$ (for details,

see Velázquez-Quesada 2022).⁷ This implies $\mathcal{L}_{PC} \leq \mathcal{L}$ and thus $\mathcal{L} \approx \mathcal{L}_{PC}$: the languages \mathcal{L} and \mathcal{L}_{PC} are equally expressive.

Model checking Now we address the complexity of the model checking problem for \mathcal{L}_{PC} by providing an algorithm that works in polynomial time (in the sizes of an input model and formula). In particular, we are interested in the *global* model checking problem.

Definition 3.3 Given a finite model $M = \langle W, R, V \rangle$ and a formula $\varphi \in \mathcal{L}_{PC}$, the *global model checking problem* for \mathcal{L}_{PC} consists in finding all $w \in W$ such that $(M, w) \models \varphi$. ◀

Given a finite pointed model (M, w) and a formula $\varphi \in \mathcal{L}_{PC}$, the model checking strategy uses an ordered list containing the subformulas that need to be evaluated for deciding whether φ holds at (M, w) . Intuitively, the ordering allows the algorithm to deal with formulas *inside* communication modalities (i.e., the χ 's in $[S:\chi]\psi$) before dealing with formulas *within the scope* of such modalities (i.e., the ψ 's in $[S:\chi]\psi$). In this way, when $[S:\chi]\psi$ needs to be evaluated, the effects of $[S:\chi]$ on the model are already known.

To obtain such a list, use a strategy similar to that in Kuijter (2015). Start by creating the set $\text{subm}(\varphi, \epsilon)$, which contains all subformulas and partial communication modalities in φ , taking additional care of labelling all these expressions with the sequence α of partial communication modalities inside the scope of which they appear (here, ϵ is the empty string). Using “.” for concatenation, the function subm is recursively defined as

$$\begin{aligned} \text{subm}(p, \alpha) &:= \{p^\alpha\} \\ \text{subm}(\neg\varphi, \alpha) &:= \{(\neg\varphi)^\alpha\} \cup \text{subm}(\varphi, \alpha) \\ \text{subm}(\varphi \wedge \psi, \alpha) &:= \{(\varphi \wedge \psi)^\alpha\} \cup \text{subm}(\varphi, \alpha) \cup \text{subm}(\psi, \alpha) \\ \text{subm}(D_G \varphi, \alpha) &:= \{(D_G \varphi)^\alpha\} \cup \text{subm}(\varphi, \alpha) \\ \text{subm}([S:\chi]\varphi, \alpha) &:= \{([S:\chi]\varphi)^\alpha, [S:\chi]^\alpha\} \cup \text{subm}(\chi, \alpha) \cup \text{subm}(\varphi, \alpha \cdot [S:\chi]) \end{aligned}$$

As an example, consider the formula $[S_1:p \wedge q][S_2:q]D_G p$. According to the definition above, the set $\text{subm}([S_1:p \wedge q][S_2:q]D_G p, \epsilon)$ is given by

$$\left\{ \begin{array}{l} [S_1:p \wedge q][S_2:q]D_G p, [S_1:p \wedge q], p \wedge q, p, q, ([S_2:q]D_G p)^{[S_1:p \wedge q]}, \\ [S_2:q]^{[S_1:p \wedge q]}, q^{[S_1:p \wedge q]}, (D_G p)^{[S_1:p \wedge q][S_2:q]}, p^{[S_1:p \wedge q][S_2:q]} \end{array} \right\}$$

Then, obtain the required ordered list by ordering the elements of $\text{subm}(\varphi, \epsilon)$ in the following way: for $\psi_1^\sigma, \psi_2^\tau$ (with σ and τ the labellings)⁸ we have that ψ_1^σ precedes ψ_2^τ if and only if

- ψ_1^σ and ψ_2^τ appear within some modalities $[S:\chi]$, and $\sigma < \tau$,⁹ or else
- ψ_1^σ appears within some $[S:\chi]$, and ψ_2^τ does not, or else

⁷Note: the translation's complexity might be exponential, as it is for similar DELs (e.g., public announcement: Lutz 2006).

⁸We would like to reiterate that since we include in $\text{subm}(\varphi, \epsilon)$ not only subformulas of φ but modalities $[S:\chi]$ appearing in φ as well, elements ψ_1^σ and ψ_2^τ are not necessarily formulas.

⁹That is, σ is a proper prefix of τ .

- ψ_1^σ is some modality $[S: \chi]$, ψ_2^τ is not, and $\sigma < \tau$, or else
- neither ψ_1^σ nor ψ_2^τ appear in some modalities $[S: \chi]$, and $\tau < \sigma$, or else
- both ψ_1^σ and ψ_2^τ are some modalities $[S: \chi]$, and $\sigma < \tau$, or else
- $\sigma = \tau$, and ψ_1^σ is either a subformula of ψ_2^τ or is a modality appearing in ψ_2^τ , or else
- ψ_1 appears to the left of χ in φ .

As an example, ordering the elements of $\text{subm}([S_1: p \wedge q][S_2: q] D_G p, \epsilon)$ yields

$$p, q, p \wedge q, [S_1: p \wedge q], q^{[S_1: p \wedge q]}, [S_2: q]^{[S_1: p \wedge q]}, p^{[S_1: p \wedge q][S_2: q]}, (D_G p)^{[S_1: p \wedge q][S_2: q]}, \\ ([S_2: q] D_G p)^{[S_1: p \wedge q]}, [S_1: p \wedge q][S_2: q] D_G p$$

Note how, for a given formula φ , the number of elements in $\text{subm}(\varphi)$ (the subformulas and partial communication modalities in φ) is bounded by $O(|\varphi|)$.

Once the list $\text{subm}(\varphi)$ is ready, run the labelling [Algorithm 1](#), which is inspired by the model checking procedure for epistemic logic ([Halpern and Moses 1992](#)). The crucial difference is that, besides labelling worlds (with the subformulas of φ that are true), the algorithm also labels relations (case $[S: \chi]^\sigma$). With this, it is possible to keep track of which relations ‘survive’ the model transformations indicated by the partial communication modalities. This labelling of relations is then used when evaluating formulas with the epistemic operators $(D_G \chi)^\sigma$: one only needs to evaluate χ in those worlds accessible via relations that have ‘survived’ up to the current stage of the run.

Algorithm 1 An algorithm for model checking for \mathcal{L}_{PC}

```

1: procedure GLOBALMC( $M, \varphi$ )
2:   for all  $\psi^\sigma \in \text{subm}(\varphi)$  do
3:     for all  $w \in W$  do
4:       case  $\psi^\sigma = p^\sigma$ 
5:         if  $w \in V(p)$  then
6:           label  $w$  with  $p^\sigma$ 
7:       case  $\psi^\sigma = (\neg \chi)^\sigma$ 
8:         if  $w$  is not labelled with  $\chi^\sigma$  then
9:           label  $w$  with  $(\neg \chi)^\sigma$ 
10:      case  $\psi^\sigma = (\chi \wedge \xi)^\sigma$ 
11:        if  $w$  is labelled with  $\chi^\sigma$  and  $\xi^\sigma$  then
12:          label  $w$  with  $(\chi \wedge \xi)^\sigma$ 
13:      case  $\psi^\sigma = (D_G \chi)^\sigma$ 
14:         $check \leftarrow true$ 
15:        for all  $(w, v) \in R_G$  do
16:          if  $(w, v)$  is labelled with  $\sigma$  then
17:            if  $v$  is not labelled with  $\chi^\sigma$  then
18:               $check \leftarrow false$ 
19:            break
20:        if  $check$  then
21:          label  $w$  with  $(D_G \chi)^\sigma$ 
22:      case  $\psi^\sigma = [S: \chi]^\sigma$ 
23:        for all  $i \in A$  do
24:          for all  $(v, u) \in R_i$  do
25:            if  $(v, u)$  is labelled with  $\sigma$  then
26:              if  $v$  is labelled with  $\chi$  iff  $u$  is labelled with  $\chi$  then
27:                label  $(v, u)$  with  $\sigma, [S: \chi]$ 
28:              else

```

```

410 29:          check ← true
411 30:          for all j ∈ S do
412 31:              if (v, u) ∉ Rj then
413 32:                  check ← false
416 33:                  break
417 34:          if check then
428 35:              label (v, u) with σ, [S: χ]
425 36:          case ψσ = ([S: χ] ξ)σ
426 37:              if w is labelled with ξσ[S: χ]} then
438 38:                  label w with ([S: χ] ξ)σ

```

Correctness of the algorithm can be shown by an induction on φ , noting that cases of the algorithm mimic the definition of semantics. From a computational perspective, the preparation of the ordered list from $\text{subm}(\varphi)$ can be done in $O(|\varphi|^2)$ steps: one loop to go over the elements of $\text{subm}(\varphi)$, and a nested loop to compare the current element ψ_1^σ to other elements ψ_2^τ according to the introduced ordering procedure. The running time of GLOBALMC is bounded by $O(|\varphi| \cdot |W| \cdot |A|^2 \cdot |R|)$ for the case of $[S: \chi]^\sigma$.

Theorem 5 *The model checking problem for \mathcal{L}_{PC} is in P.* ■

3.2 Partial communication vs. public announcements

The action of partial communication is, in a sense, related to that of a public announcement: both are epistemic actions through which agents receive information about the truth-value of a specific formula. Still, there is an important difference: while in a public announcement the information comes from an external source, in partial communication the information comes from agents in the model. It makes sense to discuss the relationship between their formal representations.

Under its standard definition (Plaza 1989), the public announcement of a formula ξ transforms a model by eliminating all $\neg\xi$ -worlds. For a fair comparison with the partial communication action, here is an alternative public announcement definition that rather removes edges connecting worlds that disagree on ξ 's truth-value (van Benthem and Liu 2007).¹⁰

Definition 3.4 (Public announcement) Let $M = \langle W, R, V \rangle$ be a model; take a formula ξ . The model $M_\xi = \langle W, R_\xi, V \rangle$, which is the result of an external source informing all the agents that ξ is the case, is defined such that

$$R_\xi^i := R_i \cap \sim_\xi^M. \quad \blacktriangleleft$$

Note how the indistinguishability relation for a group of agents G in the new model, denoted as R_G^ξ , is simply $R_G \cap \sim_\xi^M$. More importantly, in the model that results from this edge-deleting operation, the ξ -region (the partition containing the worlds satisfying ξ) is collectively P-bisimilar (and, in fact, identical) to the model produced by the standard world-removing version. Thus, when evaluating formulas on worlds in this ξ -region, the outcomes from both operations are, as far as \mathcal{L} can tell, the same. That we do stay in this region is

¹⁰Cf. Gerbrandy and Groeneveld (1997), which removes only edges pointing to $\neg\xi$ -worlds. The option used here has the advantage of behaving, with respect to the preservation of certain relational properties, as the standard definition does (see the discussion after Definition 3.4).

465 guaranteed by the precondition in the semantic interpretation of the modality
 466 $[\xi]$ below (Definition 3.5). It is also useful to notice that the operation preserves
 467 reflexivity, transitivity and symmetry: if R_i has any of those properties, then so
 468 has R_i^ξ , as it is then the intersection of two reflexive, transitive and symmetric
 469 relations.

Proposition 1 *Let $M = \langle W, R, V \rangle$ be a model, and let ξ be a formula. Recall (Plaza 1989) that the world-removing public announcement of ξ on M yields the model $M'_\xi = \langle \llbracket \xi \rrbracket^M, \{R'_i \mid i \in \mathbf{A}\}, V' \rangle$ with*

$$R'_i := R_i \cap (\llbracket \xi \rrbracket^M \times \llbracket \xi \rrbracket^M) \quad \text{and} \quad V'(p) := V(p) \cap \llbracket \xi \rrbracket^M.$$

470 Now, take any w in the domain of M'_ξ (that is, any $w \in \llbracket \xi \rrbracket^M$). Then,

471
$$(M_\xi, w) \rightleftharpoons_C (M'_\xi, w).$$

Proof. Intuitively, the difference between the world-removing and edge-deleting approaches makes no difference for a collective bisimulation: in both cases, the $\neg\xi$ -partition becomes inaccessible from the ξ -partition, where the world w lies. Formally, it is enough to prove that the relation

$$Z := \{(u, u) \in (W \times \llbracket \xi \rrbracket^M) \mid u \in \llbracket \xi \rrbracket^M\}$$

472 is a collective bisimulation (between M_ξ and M'_ξ) containing the pair (w, w) .
 473 Details can be found in the [appendix](#). ■

474 For the language, here is a modality for describing the operation's effect.

475 **Definition 3.5 (Modality $[\xi]$)** Define $\mathcal{L}_{\text{PA}}[0] := \mathcal{L}$, where PA stands for *public*
 476 *announcements*. Then, define $\mathcal{L}_{\text{PA}}[i+1]$ as the result of extending $\mathcal{L}_{\text{PA}}[i]$ with an
 477 additional modality $[\xi]$ for $\xi \in \mathcal{L}_{\text{PA}}[i]$. The language \mathcal{L}_{PA} is the union of all
 478 $\mathcal{L}_{\text{PA}}[n]$ with $n \in \mathbb{N}$, thus essentially extending \mathcal{L} with a modality $[\xi]$ for each
 479 formula ξ . The set of atoms for formulas in \mathcal{L}_{PA} is as in Definition 2.3 with the
 480 additional clause $\text{at}([\xi]\varphi) := \text{at}(\xi) \cup \text{at}(\varphi)$. For the semantic interpretation,

481
$$(M, w) \models [\xi]\varphi \quad \text{iff}_{\text{def}} \quad (M, w) \models \xi \text{ implies } (M_\xi, w) \models \varphi.$$

482 Define $\langle \xi \rangle \varphi := \neg [\xi] \neg \varphi$. Note how this implies $\models \langle \xi \rangle \varphi \leftrightarrow (\xi \wedge [\xi] \varphi)$. ◀

483 Following the strategy used in the proof of Theorem 4, it can be shown that
 484 \mathcal{L}_{PA} is invariant under collective bisimilarity.

485 **Theorem 6 (\rightleftharpoons_C implies \mathcal{L}_{PA} -equivalence)** *Let (M, w) and (M', w') be two pointed models; take $Q \subseteq P$. If $(M, w) \rightleftharpoons_C^Q (M', w')$ then, for every $\psi \in \mathcal{L}_{\text{PA}}$ with $\text{at}(\psi) \subseteq Q$,*

487
$$(M, w) \models \psi \quad \text{if and only if} \quad (M', w') \models \psi.$$

488 *Proof.* See the [appendix](#). ■

489 Finally, an axiom system can be obtained by using the reduction axioms
 490 technique, with the crucial axiom being $[\xi]D_G\varphi \leftrightarrow (\xi \rightarrow D_G[\xi]\varphi)$ (Wáng
 491 and Ågotnes 2013). As before, the existence of the reduction axioms implies
 492 $\mathcal{L}_{\text{PA}} \leq \mathcal{L}$. This, together with the straightforward $\mathcal{L} \leq \mathcal{L}_{\text{PA}}$, implies $\mathcal{L} \approx \mathcal{L}_{\text{PA}}$:

the languages \mathcal{L} and \mathcal{L}_{PA} are equally expressive. With the basics of the edge-deleting public announcement presented/recalled, it is now possible to compare it with the partial communication proposal.

When comparing the partial communication and public announcements settings, a natural question is about the languages' relative expressivity. The answer is simple: \mathcal{L}_{PC} and \mathcal{L}_{PA} are both reducible to \mathcal{L} , and thus they are equally expressive.

Then, at the semantic level, one might wonder whether the operations can 'mimic' each other. More precisely, one can ask the following.

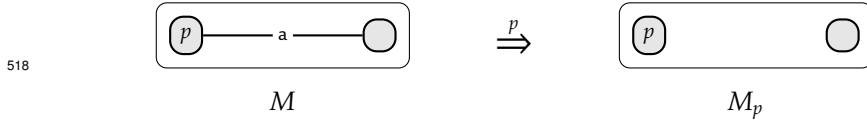
- Given $\xi \in \mathcal{L}$, are there $S \subseteq \mathbf{A}$ and $\chi \in \mathcal{L}$ such that $M_\xi \rightleftharpoons_C M_{S:\chi}$ for every M ?
In symbols: does $\forall \xi. \exists S. \exists \chi. \forall M. (M_\xi \rightleftharpoons_C M_{S:\chi})$ hold?

- Given $S \subseteq \mathbf{A}$ and $\chi \in \mathcal{L}$, is there $\xi \in \mathcal{L}$ such that $M_{S:\chi} \rightleftharpoons_C M_\xi$ for every M ?
In symbols: does $\forall S. \forall \chi. \exists \xi. \forall M. (M_{S:\chi} \rightleftharpoons_C M_\xi)$ hold?

Some known model-update operations have this relationship. For example, the action models of [Baltag et al. \(1998\)](#) generalise standard public announcements: for every formula ξ there is an action model that, when applied to any relational model, produces exactly the one that a public announcement of ξ does. For another example, edge-deleting versions of a public announcement (both that in [Gerbrandy and Groeneveld 1997](#) and that in [Definition 3.4](#), borrowed from [van Benthem and Liu 2007](#)) can be represented within the arrow update framework of [Kooi and Renne \(2011\)](#), as it will be discussed later ([Subsection 3.3](#)).

Here, the answer to the first question is straightforward: the agents might not have, even together, the information that a public announcement provides.

Fact 1 Take $\mathbf{A} = \{a\}$ and $\mathbf{P} = \{p\}$; consider the (reflexive and symmetric) model M below on the left. A public announcement of p yields the model M_p on the right.

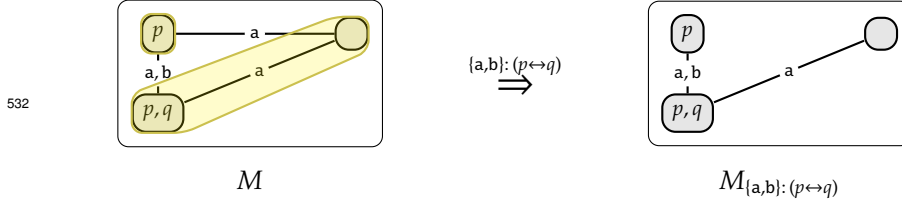


Now, there are no $S \subseteq \mathbf{A}$ and $\chi \in \mathcal{L}$ such that $M_{S:\chi} \rightleftharpoons_C M_p$. The group S can be only \emptyset or $\{a\}$ and, in both cases, $R^{S:\chi}_a = R_a$, regardless of the formula χ . ■

Thus, $\forall M. \forall \xi. \exists S. \exists \chi. (M_\xi \rightleftharpoons_C M_{S:\chi})$ fails: for the given model, the effect of a public announcement of p cannot be replicated by any act of partial communication. This answers negatively the (stronger) first question above: there are no agents S and topic χ that can replicate the given public announcement in every model.

The answer to the second question is interesting: through partial communication, the agents can reach epistemic situations that cannot be reached by a public announcement.

Fact 2 Take $\mathbf{A} = \{a, b\}$ and $\mathbf{P} = \{p, q\}$; consider the (reflexive and symmetric) model M below on the left. A partial communication between all agents about $p \leftrightarrow q$ (equivalence classes highlighted) yields the model $M_{\{a,b\}:(p \leftrightarrow q)}$ on the right.



533 Now, there is no $\xi \in \mathcal{L}$ such that $M_\xi \rightleftharpoons_C M_{[a,b]: (p \leftrightarrow q)}$. For this, note that a public
 534 announcement preserves the transitivity of indistinguishability relations; yet, while all
 535 relations in M are transitive, that for a in $M_{[a,b]: (p \leftrightarrow q)}$ is not. ■

536 Thus, $\forall M. \forall S. \forall \chi. \exists \xi. (M_{S:\chi} \rightleftharpoons_C M_\xi)$ fails: for the given model, the effect
 537 of a ‘conversation’ among a and b on $p \leftrightarrow q$ cannot be replicated by any public
 538 announcement. This answers negatively the (stronger) second question above:
 539 there is no χ that can replicate the given partial communication in every model.

540 3.3 Partial communication vs. arrow updates

541 While a public announcement removes *all* edges between worlds disagreeing
 542 on the truth-value of the given formula, the *arrow update* framework (Kooi and
 543 Renne 2011) allows for a more refined transformation of a model’s relations. An
 544 arrow update U is a finite set of edge specifications represented by triples of the
 545 form (ξ, i, χ) . Intuitively, each triple in U prescribes to retain, in the updated
 546 model, those edges labelled with i that go from a ξ -world to a χ -world. In this
 547 way, arrow updates can target particular edges in a model.

548 **Definition 3.6 (Modality $[U]$)** Define $\mathcal{L}_{AU}[0] := \mathcal{L}$, where AU stands for *ar-*
 549 *row updates*. Then, define $\mathcal{L}_{AU}[i+1]$ as the result of extending $\mathcal{L}_{AU}[i]$ with
 550 an additional modality $[U]$, for U a finite list $(\xi_1, i_1, \chi_1), \dots, (\xi_m, i_m, \chi_m)$ with
 551 $\xi_j, \chi_j \in \mathcal{L}_{AU}[i]$ and $i_j \in A$ for $1 \leq j \leq m$. The language \mathcal{L}_{AU} is the union of all
 552 $\mathcal{L}_{AU}[n]$ with $n \in \mathbb{N}$. The set of atoms for formulas in \mathcal{L}_{AU} is as in Definition 2.3
 553 plus the clause $\text{at}([U]\varphi) := \bigcup_{(\xi, i, \chi) \in U} (\text{at}(\xi) \cup \text{at}(\chi)) \cup \text{at}(\varphi)$. The semantics of
 554 arrow update formulas is defined as

$$555 \quad (M, w) \models [U]\varphi \quad \text{iff}_{\text{def}} \quad (M_U, w) \models \varphi,$$

556 where $M_U = \langle W, R^U, V \rangle$ and

$$557 \quad R^U_i := \{(u, u') \in R_i \mid \exists (\xi, i, \chi) \in U : (M, u) \models \xi \text{ and } (M, u') \models \chi\}. \quad \blacktriangleleft$$

558 For structural invariance, that collectively bisimilarity implies equivalence
 559 w.r.t. formulas in \mathcal{L}_{AU} can be shown by a straightforward extension of the
 560 corresponding proof (van Ditmarsch et al. 2017, Lemma 3) for the original arrow
 561 update language, which lacks the distributed knowledge modality (instead
 562 using only knowledge modalities for single agents; Kooi and Renne 2011).

563 **Theorem 7 (\rightleftharpoons_C implies \mathcal{L}_{AU} -equivalence)** Let (M, w) and (M', w') be two poin-
 564 ted models; take $Q \subseteq P$. If $(M, w) \rightleftharpoons_C^Q (M', w')$ then, for every $\psi \in \mathcal{L}_{AU}$ with $\text{at}(\psi) \subseteq Q$,

$$565 \quad (M, w) \models \psi \quad \text{if and only if} \quad (M', w') \models \psi. \quad \blacksquare$$

For the axiomatisation, we need to resolve a technicality. The original arrow update language lacks the distributed knowledge modality, but the just-defined \mathcal{L}_{AU} uses it. Thus, we cannot reuse reduction axioms of the original paper ‘as is’; some gentle modification is required.

The crucial reduction axiom from Kooi and Renne (2011) is

$$[U]K_i \varphi \leftrightarrow \bigwedge_{(\xi, i, \chi) \in U} (\xi \rightarrow K_i(\chi \rightarrow [U]\varphi)).$$

Now, given an arrow update U and a group of agents G , we can construct sets of triples of the form $\{(\bigwedge_{i \in G} \xi_i, i, \bigwedge_{i \in G} \chi_i) \mid i \in G\}$, where for each $i \in G$ there is one ξ_i (resp. one χ_i) in $\bigwedge_{i \in G} \xi_i$ (resp. $\bigwedge_{i \in G} \chi_i$) such that $(\xi_i, i, \chi_i) \in U$. Setting $\xi_G := \bigwedge_{i \in G} \xi_i$ and $\chi_G := \bigwedge_{i \in G} \chi_i$, the set of all such triples $\{(\xi_G, i, \chi_G) \mid i \in G\}$ is denoted by U^G . Intuitively, an edge labelled with G from u to u' is preserved in a model M if there are triples $\{(\xi_G, i, \chi_G) \mid i \in G\} \subseteq U^G$ such that $(M, u) \models \xi_G$ and $(M, u') \models \chi_G$ for each $i \in G$. Hence, the reduction axiom for the interaction of arrow updates and distributed knowledge is

$$[U]D_G \varphi \leftrightarrow \bigwedge_{\{(\xi_G, i, \chi_G) \mid i \in G\} \subseteq U^G} (\xi_G \rightarrow D_G(\chi_G \rightarrow [U]\varphi)).$$

The soundness of the axiom can be shown similarly to the soundness proof from Kooi and Renne (2011). The completeness of the system resulting from adding this axiom can be proved with the standard ‘reduction axioms’ technique. This shows that \mathcal{L} and \mathcal{L}_{AU} are equally expressive, which then implies that so are the latter and the partial communication language \mathcal{L}_{PC} .

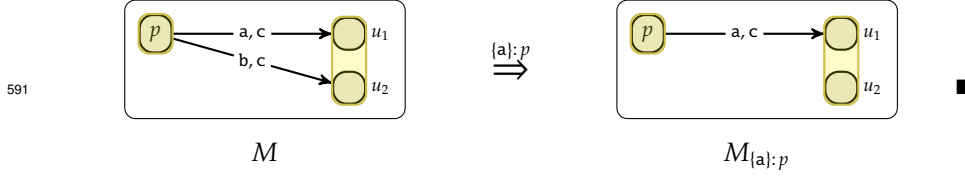
This changes slightly once we compare update expressivity. On the one hand, the effects of certain arrow updates cannot be replicated by partial communication. This follows from Fact 1 and the fact that the effect of an edge-removing public announcement with ξ (Definition 3.4) can be modelled by the arrow update $\{(\xi, i, \xi), (\neg\xi, i, \neg\xi) \mid i \in A\}$.¹¹

Fact 3 Take $A = \{a\}$ and $P = \{p\}$; consider the (reflexive and symmetric) models M and M_p from Fact 1. When applied to M , the arrow update $U := \{(p, a, p), (\neg p, a, \neg p)\}$ will produce the model M_p . Still, as argued in Fact 1, no partial communication can transform M into a model that is collectively bisimilar to M_p . ■

On the other hand, partial communication modalities can cut relations to collectively bisimilar states, which cannot be replicated by any arrow updates. Hence, partial communication and arrow updates are, update expressivity wise, incomparable.

Fact 4 Take $A = \{a, b, c\}$ and $P = \{p\}$; consider the model M below on the left. A partial communication of agent a on topic p (equivalence classes highlighted) yields the model $M_{\{a\}:p}$ on the right.

¹¹As shown in Kooi and Renne (2011), arrow updates can also mimic the version of public announcements from Gerbrandy and Groeneveld (1997), which removes only edges pointing to $\neg\xi$ -worlds (via the arrow update $\{(\top, i, \xi) \mid i \in A\}$) as well as the world removing versions from (Plaza 1989) (via $\{(\top, i, \xi) \mid i \in A\}$ and an adequate additional modality).



592 However, there is no arrow update U such that M_U is collectively bisimilar to $M_{[a]:p}$.
 593 For doing so, one would need a clause (ξ, c, χ) in U with a formula $\chi \in \mathcal{L}_{AU}$ that is,
 594 in M , true at u_1 (so the c -edge to u_1 is preserved) but false at u_2 (so the c -edge to
 595 u_2 is removed). However, this is impossible: u_1 and u_2 are collectively bisimilar to
 596 one another (both are dead-end states), and thus they cannot be distinguished by the
 597 language.

598 3.4 Discussion

599 This section has studied further the partial communication framework. Thus,
 600 it makes sense to argue for its use, contrasting the choices made with their
 601 alternatives.

602 A first concern might be that, while communication between agents is a cru-
 603 cial form of interaction, it can be already modelled through public announce-
 604 ments (e.g., Ågotnes et al. 2010, van Ditmarsch 2014). Still, this strategy might
 605 not be fully suited. In such a setting, an announcement requires, in fact, two
 606 parameters: the announcement's precondition and the information the agents
 607 receive. When the announcement comes from a 'nameless' external source, it
 608 is clear what these two parameters are, and they turn out to be the same: to be
 609 'announced', ξ must be true (the precondition), and the agents learn that ξ is
 610 the case (the information).¹² But when the information comes from an agent,
 611 precondition and information content are not straightforward, and they might
 612 differ. When an agent i announces ξ , what is the precondition? There is an an-
 613 nouncer involved, so it cannot be only ξ . Is it enough that the announcer knows
 614 ξ (i.e., $K_i \xi$), or should she be introspective about it (i.e., $K_i K_i \xi$)? Analogously,
 615 what is what the other agents learn? Assuming they trust the announcer, they
 616 learn that ξ is true. Do they also learn that the announcer knows ξ (i.e., $K_i \xi$),
 617 or even that she knows that she knows ξ (i.e., $K_i K_i \xi$)?

618 These questions naturally extend to situations of group communication.
 619 In group announcement logic (Ågotnes et al. 2010), an announcement from a
 620 group S is represented by the public announcement of $\bigwedge_{i \in S} K_i \xi_i$, a conjunction
 621 specifying a formula ξ_i known by each agent i . In other words, an announce-
 622 ment from a group S is modelled as a parallel action in which each agent $i \in S$
 623 announces a formula she knows. However, other readings may be more ap-
 624 propriate: the group might announce something that is common knowledge
 625 among its members, or even announce something they all know distributively.
 626 These alternative readings are more naturally represented by the actions intro-
 627 duced in Baltag (2010), Ågotnes and Wáng (2017), Baltag and Smets (2020), of
 628 which partial communication is just a (topic-oriented) variation.

629 Then, in the partial communication setting, although only some of the agents
 630 share, this information is received by every agent. This 'everybody hears' set-

¹²More precisely, they learn that ξ was the case at the moment of its announcement.

ting is useful, e.g., for modelling classroom scenarios where (hopefully) everybody listens to what is being told, but only the lecturer and some adventurous students communicate. It can be also used for representing situations similar to public debates, where everybody ‘hears’ but only the appointed ones get to ‘talk’. It can even be used when the communication channel is insecure, and thus privacy cannot be assumed. Of course, it is also interesting to look into more complex ‘private communication’ scenarios, such as those in which only some agents receive the shared information.¹³ Instead, this paper has rather focused on the strategic aspects that arise in competitive situations. In such cases, one naturally wonders whether there is a form of partial communication that can achieve a given goal (e.g., [van Ditmarsch 2003](#)). The arbitrary partial communication of [Section 4](#) can help to answer such questions.

4 Arbitrary partial communication

The partial communication framework allows us to model inter-agent information exchange. Yet, consider competitive scenarios. While it is interesting to find out what a form of partial communication can achieve (fix the agents and the topic, then find the consequences), one might be also interested in deciding whether a given goal can be achieved by *some* form of partial communication (fix the *goal*: is there a group of agents and a topic that can achieve it?). This *quantification* over the sharing agents and the topic they discuss adds a strategic dimension to the framework. This is particularly useful when communication occurs over an insecure channel, as one would like to know *whether* there is a form of partial communication (who talks, and on which topic) that can achieve a given goal (e.g., make something common knowledge for a group of agents, while also precluding adversaries/eavesdroppers from learning it, as in [van Ditmarsch 2003](#)). Thus, in the spirit of [Balbiani et al. \(2008\)](#), one can then *quantify*, either over the agents that communicate or over the topic they discuss.

Quantifying over the communicating agents does not need additional machinery: A is finite, so a modality stating that “ φ is true after any group of agents share all their information about χ ” is definable as $[*: \chi] \varphi := \bigwedge_{S \subseteq A} [S: \chi] \varphi$ (and thus, by defining $\langle *: \chi \rangle \varphi := \neg [*: \chi] \neg \varphi$, it follows that $\models \langle *: \chi \rangle \varphi \leftrightarrow \bigvee_{S \subseteq A} \langle S: \chi \rangle \varphi$). Hence, in the rest of the section we focus on quantification over topics.

4.1 Syntax, semantics, and model checking

Definition 4.1 (Modality $[S: *]$) Define $\mathcal{L}_{PC}^*[0]$ as \mathcal{L} plus the *quantifying* modality $[S: *]$. Then, define $\mathcal{L}_{PC}^*[i+1]$ as the result of extending $\mathcal{L}_{PC}^*[i]$ with an additional modality $[S: \chi]$ for $S \subseteq A$ and $\chi \in \mathcal{L}_{PC}^*[i]$. The language \mathcal{L}_{PC}^* is the union of all $\mathcal{L}_{PC}^*[n]$ with $n \in \mathbb{N}$, thus essentially extending \mathcal{L}_{PC} with a modality $[S: *]$ for each group of agents $S \subseteq A$. The set of atoms and size for $\varphi \in \mathcal{L}_{PC}^*$ extend [Definition 3.2](#) with the clauses $\text{at}([S: *] \varphi) := \text{at}(\varphi)$ and $|[S: *] \varphi| := |\varphi| + 1$, respectively. For the semantic interpretation,

$$\begin{aligned} (M, w) \models [S: *] \varphi & \text{ iff}_{def} (M, w) \models [S: \chi] \varphi \text{ for every } \chi \in \mathcal{L} \\ & \text{ iff } (M_{S, \chi}, w) \models \varphi \text{ for every } \chi \in \mathcal{L}. \end{aligned}$$

¹³The interested reader is referred, e.g., to the semi-private communication within groups of [Ågotnes and Wáng \(2017\)](#) and the secret ‘hacking’ from [Baltag and Smets \(2020\)](#).

$A_{S: \cdot} :$	$\vdash [S: \cdot] \varphi \rightarrow [S: \chi] \varphi$	for every $\chi \in \mathcal{L}$
$R_{S: \cdot} :$	If $\vdash \eta([S: \chi] \varphi)$ for all $\chi \in \mathcal{L}$, then $\vdash \eta([S: \cdot] \varphi)$	

Table 3: Axiom and rule of inference for the arbitrary case.

672 If one defines $\langle S: \cdot \rangle \varphi := \neg [S: \cdot] \neg \varphi$, then

673 $(M, w) \models \langle S: \cdot \rangle \varphi$ iff_{def} there is $\chi \in \mathcal{L}$ such that $(M_{S: \chi}, w) \models \varphi$. \blacktriangleleft

674 Note how $[S: \cdot]$ quantifies over formulas in \mathcal{L} , and not over formulas in \mathcal{L}_{PC}^* .
 675 As in [Balbiani et al. \(2008\)](#), this is to avoid circularity issues. One could have
 676 also chosen to quantify over formulas in \mathcal{L}_{PC} , but $\mathcal{L} \approx \mathcal{L}_{PC}$ (see the paragraph
 677 on expressivity on [Page 9](#)) so nothing is lost by using \mathcal{L} instead.¹⁴ Note also
 678 how, because of the way \mathcal{L}_{PC}^* is defined ($[S: \cdot]$ is added at the beginning and
 679 not at the end), the topic χ of a partial communication formula $[S: \chi] \varphi$ might
 680 contain arbitrary partial communication modalities (just as publicly announced
 681 formulas might contain arbitrary public announcement modalities in [Balbiani](#)
 682 [et al. 2008](#)).

683 **Axiom system.** Axiomatising \mathcal{L}_{PC}^* requires an additional notion.

Definition 4.2 (Necessity Forms) Given a symbol $\# \notin P$, the set of *necessity forms* ([Goldblatt 1982](#)) is given by

$$\eta(\#) ::= \# \mid \phi \rightarrow \eta(\#) \mid D_G \eta(\#) \mid [S: \chi] \eta(\#)$$

684 with ϕ an \mathcal{L}_{PC}^* -formula, χ an \mathcal{L} -formula, and sets of agents $S, G \subseteq A$. In a
 685 necessity form $\eta(\#)$, replacing $\#$ with a \mathcal{L}_{PC}^* -formula ψ produces another \mathcal{L}_{PC}^* -
 686 formula, denoted as $\eta(\psi)$. \blacktriangleleft

687 The (note: *infinitary*) axiom system for \mathcal{L}_{PC}^* , similar to well-known axiomat-
 688 isations of other logics of quantified epistemic actions (see [van Ditmarsch 2023](#)
 689 for an overview), is given by the axioms and rules on [Tables 1, 2 and 3](#). The
 690 axiom $A_{[S: \cdot]}$ and the rule $R_{[S: \cdot]}$ ([Table 3](#)) are the crucial ones for the modality
 691 for arbitrary partial communication, and their soundness follows from $[S: \cdot]$'s
 692 semantic interpretation. The completeness of the whole system can be proved
 693 by combining and adapting techniques from [Wáng and Ågotnes \(2013\)](#) (to deal
 694 with distributed knowledge) and [Balbiani and van Ditmarsch \(2015\)](#) (to tackle
 695 the quantifying modalities).¹⁵

696 **Theorem 8** *The axioms and rules on [Tables 1, 2 and 3](#) are sound and (together)*
 697 *complete for \mathcal{L}_{PC}^* .*

698 *Proof.* See the [appendix](#). \blacksquare

¹⁴Still, for languages with other types of group knowledge, adding a dynamic modality might influence the expressive power. For more on this (in the context of common knowledge and quantified announcements), the reader is referred to [Galimullin and Ågotnes \(2021\)](#) and [Ågotnes and Galimullin \(2023\)](#).

¹⁵A relatively similar completeness proof, for a system with distributed knowledge and quantification over public announcements, is presented in [Ågotnes et al. \(2022\)](#).

699 **Structural equivalence.** The quantifying modality $[S: *]$ is also invariant under
700 collective bisimilarity.

701 **Theorem 9 ($\not\Rightarrow_C$ implies \mathcal{L}_{PC}^* -equivalence)** Let (M, w) and (M', w') be two poin-
702 ted models; take $Q \subseteq P$. If $(M, w) \not\Rightarrow_C^Q (M', w')$ then, for every $\psi \in \mathcal{L}_{PC}^*$ with $\text{at}(\psi) \subseteq Q$,

$$703 \quad (M, w) \Vdash \psi \quad \text{if and only if} \quad (M', w') \Vdash \psi.$$

704 *Proof.* As the [proof](#) of [Theorem 4](#). For details, see the [appendix](#). ■

705 **Expressivity.** Even though the partial communication modality $[S: \chi]$ does not
706 increase the expressivity of the basic language \mathcal{L} , the modality $[S: *]$ makes \mathcal{L}_{PC}
707 more expressive. The intuition for this is that the quantifying modality allows
708 us to talk about formulas of arbitrary finite modal depth, as well as formulas
709 containing atoms that do not appear explicitly in the formula. Using either of
710 these features, one can derive a contradiction from the assumption that \mathcal{L}_{PC}
711 and \mathcal{L}_{PC}^* are equally expressive.

712 **Theorem 10** The language \mathcal{L}_{PC}^* is strictly more expressive than \mathcal{L}_{PC} .

713 *Proof. (Sketch)* This result can be proved as the analogous result for arbitrary
714 public announcements ([Balbiani et al. 2008](#), Proposition 3.13) and arbitrary
715 group announcements ([Ågotnes et al. 2022](#)). Assume, towards a contradiction,
716 that \mathcal{L}_{PC}^* and \mathcal{L}_{PC} are equally expressive. Then, given a formula in \mathcal{L}_{PC}^* , there
717 is a logically equivalent formula in \mathcal{L}_{PC} . Now, this formula in \mathcal{L}_{PC} has only a
718 finite number of atoms, and thus one can find an atom p that does not appear
719 in it. However, $[S: *]$ in \mathcal{L}_{PC}^* quantifies over any formula, and thus also over
720 formulas including p . With this, one can build two models where this atom p
721 plays a ‘distinguishing’ role. Then, using induction, it can be shown that the
722 formula in \mathcal{L}_{PC} (without p) cannot tell the models apart, while the formula in
723 \mathcal{L}_{PC}^* (where quantification ranges also over formulas with p) can. ■

724 **Model checking** As it is shown below ([Theorem 11](#)), the complexity of the
725 model checking problem for \mathcal{L}_{PC}^* is $PSPACE$ -complete. This is in line with the
726 $PSPACE$ -completeness of many other logics of quantified information change,
727 as arbitrary public announcements ([Balbiani et al. 2008](#)), group announcement
728 logic ([Ågotnes et al. 2010](#)), coalition announcement logic ([Alechina et al. 2021](#))
729 and arbitrary arrow update logic ([van Ditmarsch et al. 2017](#)). However, the
730 witness algorithm presented below has an interesting twist. Model checking
731 algorithms for the aforementioned logics include a step of computing a bisim-
732 ulation contraction of a model, after which the work continues on the contracted
733 model. This is not possible here: a model and its *collective* bisimulation contrac-
734 tion are not collectively bisimilar ([Roelofsen 2005](#)), so they might differ in some
735 formulas’ truth-value. The algorithm below still computes bisimulation contrac-
736 tions, but uses them just to keep track of bisimilar worlds. The computation
737 continues on the original non-contracted model.

738 For the complexity result, the definition and fact below will be useful.

739 **Definition 4.3 (S-definable restrictions)** Let (M, w) be a pointed model; take
740 $S \subseteq A$. A model (N, w) is an S -definable restriction of (M, w) if and only if
741 $(N, w) = (M_{S: \chi}, w)$ for some $\chi \in \mathcal{L}_{PC}^*$. ◀

742 **Fact 5** Let (M, w) be a finite pointed model. Then there is a finite number of S-definable
 743 restrictions of (M, w) . ■

744 The PSPACE complexity of the model checking problem for \mathcal{L}_{PC}^* relies on
 745 an algorithm $MC(M, w, \varphi)$ that returns *true* if and only if $(M, w) \models \varphi$, and re-
 746 turns *false* if and only if $(M, w) \not\models \varphi$. The main challenge is that modalities
 747 $[S: *]$ quantify over an *infinite* number of formulas. However, for any given
 748 finite model M , there is only a *finite* number of possible S-definable model
 749 restrictions (Fact 5). The proof of the fact that the problem is PSPACE-hard
 750 uses the classic reduction from the satisfiability of QBF, which is known to be
 751 PSPACE-complete.

752 **Algorithm 2** An algorithm for model checking for \mathcal{L}_{PC}^*

```

753 1: procedure  $MC(M, w, \varphi)$ 
754 2:   case  $\varphi = [S: \chi] \psi$ 
755 3:     return  $MC(M_{S, \chi}, w, \psi)$ 
756 4:   case  $\varphi = [S: *] \psi$ 
757 5:     Compute collective P-bisimulation contraction  $|M|^C$ 
758 6:     for all S-definable restrictions  $(N, w)$  of  $(M, w)$  do
759 7:       if  $MC(N, w, \psi)$  returns false then
760 8:         return false
761 9:     return true

```

767 **Theorem 11** The model checking for \mathcal{L}_{PC}^* is PSPACE-complete.

768 *Proof. (Sketch)* Let (M, w) be a pointed model; take $\varphi \in \mathcal{L}_{PC}^*$. In Algorithm 2,
 769 Boolean cases and the case for D_G are as expected, and thus omitted. The case
 770 for $[S: *]$ relies on the construction of S-definable restrictions. The basic idea for
 771 that is to consider a subset of all possible bipartitions of (M, w) , taking care that
 772 bisimilar worlds end up in the same partition. This can be done by checking
 773 that, for each world, if it is in a partition, then all worlds in the same collec-
 774 tive bisimulation equivalence class are also in the same partition. Collective
 775 bisimulation equivalence classes can be computed by, e.g., a modification of
 776 Kanellakis-Smolka algorithm (Kanellakis and Smolka 1990) that runs in poly-
 777 nomial time and takes into account not only individual relations but also their
 778 intersections. Having computed collective bisimulation equivalence classes of
 779 (M, w) , one can construct an S-definable restriction of the model by taking a bi-
 780 partition such that if v belongs to one partition, then all $u \in [v]$ also belong to the
 781 same partition, with $[v]$ being a collective bisimulation equivalence class. For
 782 an argument that the algorithm is in PSPACE, as well as that it is PSPACE-hard,
 783 see the Appendix.

784 4.2 Arbitrary partial communication vs. arbitrary public an- 785 nouncements

786 Subsection 3.2 showed that the languages of partial communication (\mathcal{L}_{PC}) and
 787 public announcements (\mathcal{L}_{PA}) are equally expressive. As this subsection shows,
 788 this changes when quantifying modalities are added (the arbitrary partial com-
 789 munication of this section vs the arbitrary public announcements of Balbiani
 790 et al. 2008). First, the definitions for arbitrary public announcements.

791 **Definition 4.4** Define $\mathcal{L}_{PA}^*[0]$ as \mathcal{L} plus the *quantifying* modality $[*]$. Then,
 792 define $\mathcal{L}_{PA}^*[i+1]$ as the result of extending $\mathcal{L}_{PA}^*[i]$ with an additional modality
 793 $[\xi]$ for $\xi \in \mathcal{L}_{PA}^*[i]$. The language \mathcal{L}_{PA}^* is the union of all $\mathcal{L}_{PA}^*[i]$ with $i \in \mathbb{N}$, thus
 794 essentially extending \mathcal{L}_{PA} with a modality $[*]$. The set of atoms for formulas
 795 in \mathcal{L}_{PA}^* is as in [Definition 3.5](#) plus the clause $\text{at}([*]\varphi) := \text{at}(\varphi)$. For the semantic
 796 interpretation,

$$797 \quad (M, w) \models [*]\varphi \text{ iff}_{def} (M, w) \models [\xi]\varphi \text{ for every } \xi \in \mathcal{L}. \quad 16$$

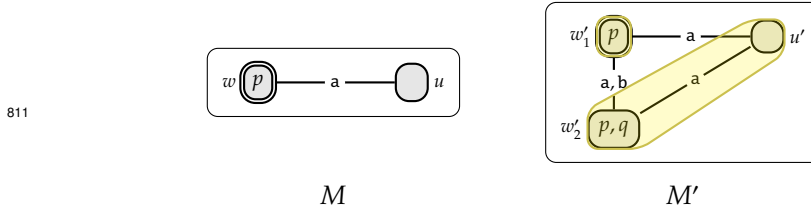
798 If one defines $\langle * \rangle \varphi := \neg [*]\neg \varphi$, then

$$799 \quad (M, w) \models \langle * \rangle \varphi \text{ iff there is } \xi \in \mathcal{L} \text{ such that } (M, w) \models \langle \xi \rangle \varphi. \quad \blacktriangleleft$$

800 The theorem below shows that \mathcal{L}_{PA}^* and \mathcal{L}_{PC}^* are incomparable with respect
 801 to expressive power (i.e., $\mathcal{L}_{PC}^* \not\leq \mathcal{L}_{PA}^*$ and $\mathcal{L}_{PA}^* \not\leq \mathcal{L}_{PC}^*$). This result is obtained by
 802 adapting techniques and models from [Balbiani et al. \(2008\)](#) and [van Ditmarsch](#)
 803 [et al. \(2017\)](#) to this partial communication case.

804 **Theorem 12** \mathcal{L}_{PA}^* and \mathcal{L}_{PC}^* are, expressivity-wise, incomparable.

805 *Proof.* For showing $\mathcal{L}_{PC}^* \not\leq \mathcal{L}_{PA}^*$, consider $\langle \{a, b\} : * \rangle (K_b p \wedge \neg K_b K_b p)$ in \mathcal{L}_{PC}^* . For
 806 a contradiction, assume there is an equivalent $\alpha \in \mathcal{L}_{PA}^*$. Since α is finite there is
 807 an atom, say q , that does not occur in it. The strategy consists in building two
 808 collectively $P \setminus \{q\}$ -bisimilar pointed models and then argue that, while they can
 809 be distinguished by $\langle \{a, b\} : * \rangle (K_a p \wedge \neg K_a K_a p)$, they cannot be distinguished
 810 by α . Consider, then, the (reflexive and symmetric) models below for $A = \{a, b\}$.



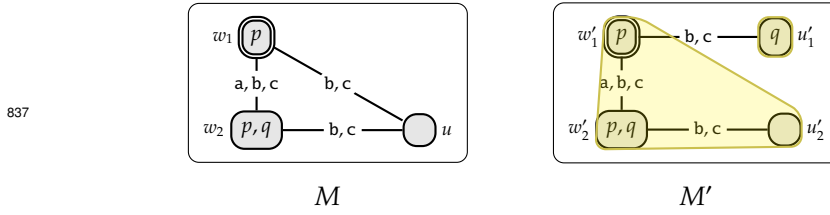
812 Now, observe the following.

- 813 • The formula $\langle \{a, b\} : * \rangle (K_a p \wedge \neg K_a K_a p)$ in \mathcal{L}_{PC}^* can tell (M, w) and (M', w'_1)
 814 apart. On the one hand, it fails at (M, w) : making $K_a p \wedge \neg K_a K_a p$ true at w
 815 requires removing the symmetric a -edge between w and u (so $K_a p$ holds),
 816 but this makes u inaccessible for a from w (thus $\neg K_a K_a p$ fails). On the
 817 other hand, it holds at (M', w'_1) : a ‘conversation’ among $\{a, b\}$ about $p \leftrightarrow q$
 818 produces the desired result ([Fact 2](#)).
- 819 • The q -less formula α in \mathcal{L}_{PA}^* , assumed to be logically equivalent to the distin-
 820 guishing $\langle \{a, b\} : * \rangle (K_a p \wedge \neg K_a K_a p)$ in \mathcal{L}_{PC}^* , cannot tell (M, w) and (M', w'_1)
 821 apart. To show this, proceed by structural induction over α . The atomic,
 822 Boolean, epistemic and public announcement cases follow from [Theorem 6](#)
 823 and the fact that the pointed models are collectively $P \setminus \{q\}$ -bisimilar, witness
 824 the relation $\{(w, w'_1), (w, w'_2), (u, u')\}$. For $[*]$ note that, for every announce-
 825 ment in one pointed model, there is a corresponding announcement in the
 826 other such that the resulting models remain collectively $P \setminus \{q\}$ -bisimilar. This

¹⁶Note: \mathcal{L}_{PA}^* extends the language in [Balbiani et al. \(2008\)](#) with distributed knowledge modalities.

is because, in both models, each world is uniquely defined by a Boolean formula containing only atoms p and q . Hence, the aforementioned collective $P \setminus \{q\}$ -bisimulation tells us how to mimic announcements. For example, if a formula ξ with $\llbracket \xi \rrbracket^{M'} = \{w'_1, w'_2\}$ is announced on M' , one can use the characterising formulas for the collective $P \setminus \{q\}$ -bisimilar w to create, in M , a matching announcement.

For showing $\mathcal{L}_{PA}^* \not\equiv \mathcal{L}_{PC}^*$, proceed in a similar fashion: consider $\langle * \rangle (K_b p \wedge \neg K_b K_b p)$ in \mathcal{L}_{PA}^* and assume there is an equivalent $\beta \in \mathcal{L}_{PC}^*$. Let q be an atom not occurring in β , and consider the (reflexive and symmetric) models below for $A = \{a, b, c\}$.



Now, observe the following.

- The formula $\langle * \rangle (K_b p \wedge \neg K_b K_b p)$ in \mathcal{L}_{PA}^* can tell (M, w_1) and (M', w'_1) apart. On the one hand, it fails at (M, w_1) , as an announcement preserves transitivity. On the other hand, it holds at (M', w'_1) : the announcement of $q \rightarrow p$ (equivalence classes highlighted) produces the desired result.
- The q -less formula β in \mathcal{L}_{PC}^* , assumed to be logically equivalent to the distinguishing $\langle * \rangle (K_b p \wedge \neg K_b K_b p)$ in \mathcal{L}_{PA}^* , cannot tell (M, w_1) and (M', w'_1) apart. To show this, proceed by structural induction over β . The atomic, Boolean, epistemic and partial communication cases follow from [Theorem 4](#) and the fact that the pointed models are collectively $P \setminus \{q\}$ -bisimilar, witness the relation $\{(w_1, w'_1), (w_2, w'_2), (u, u'_1), (u, u'_2)\}$. For $\langle S; * \rangle$ note that, for every partial communication in one pointed model, there is a corresponding partial communication in the other such that the resulting models remain collectively $P \setminus \{q\}$ -bisimilar. As in the previous case, this is because, in both models, each world is uniquely defined by a Boolean formula containing only atoms p and q . Hence, the aforementioned collective $P \setminus \{q\}$ -bisimulation tells us how to mimic partial communication. For example, if a set of agents S communicate on M' about a formula χ with $\llbracket \chi \rrbracket^{M'} = \{w'_1, u'_1\}$, one can use the characterising formulas for the collective $P \setminus \{q\}$ -bisimilar w_1 and u to create, in M , a matching topic for the same communicating agents. ■

4.3 Arbitrary partial communication vs. arbitrary arrow updates

[Subsection 3.3](#) showed that the languages of partial communication (\mathcal{L}_{PC}) and arrow updates (\mathcal{L}_{AU}) are equally expressive, relying on their reduction to the underlying epistemic logic. Similarly to the previous subsection, allowing quantification over arrow updates ([van Ditmarsch et al. 2017](#)) produces a logic that is incomparable to both \mathcal{L}_{PA}^* ([van Ditmarsch et al. 2017](#), Theorem 1) and \mathcal{L}_{PC}^* (shown below).

Definition 4.5 Define $\mathcal{L}_{\text{AU}}^*[0]$ as \mathcal{L} plus the *quantifying* modality $[*_U]$. Then, define $\mathcal{L}_{\text{AU}}^*[i+1]$ as the result of extending $\mathcal{L}_{\text{AU}}^*[i]$ with an additional modality $[U]$, where U is a finite list $(\xi_1, i_1, \chi_1), \dots, (\xi_m, i_m, \chi_m)$ with $\xi_j, \chi_j \in \mathcal{L}_{\text{AU}}^*[i]$ and $i_j \in \mathbf{A}$ for $1 \leq j \leq m$. The language $\mathcal{L}_{\text{AU}}^*$ is the union of all $\mathcal{L}_{\text{AU}}^*[n]$ with $n \in \mathbb{N}$, thus essentially extending \mathcal{L}_{AU} with a modality $[*_U]$. The set of atoms for formulas in $\mathcal{L}_{\text{AU}}^*$ is as in [Definition 3.6](#) plus the clause $\text{at}([*_U]\varphi) := \text{at}(\varphi)$. For the semantic interpretation,

$(M, w) \models [*_U]\varphi \iff_{\text{def}} (M, w) \models [U]\varphi$ for every $U \in \mathcal{L}_{\text{AU}}$. ¹⁷

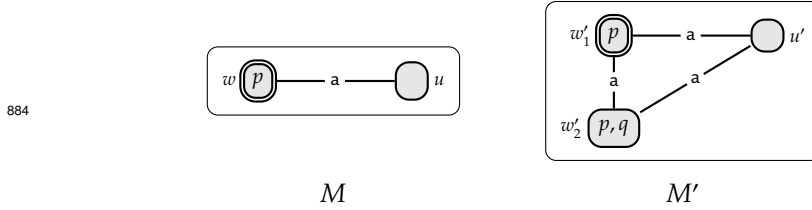
If one defines $\langle *_U \rangle \varphi := \neg [*_U] \neg \varphi$, then

$(M, w) \models \langle *_U \rangle \varphi \iff (M, w) \models \langle U \rangle \varphi$ for some $U \in \mathcal{L}_{\text{AU}}$. \blacktriangleleft

Similarly to [Theorem 12](#), we can show that quantifying over partial communication and quantifying over arrow updates are incomparable to each other. Below we present a proof sketch of this result.

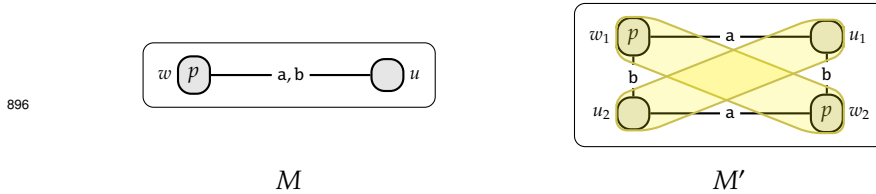
Theorem 13 $\mathcal{L}_{\text{PC}}^*$ and \mathcal{L}_{U}^* are, expressivity-wise, incomparable.

Proof. (Sketch) To see that $\mathcal{L}_{\text{AU}}^* \not\equiv \mathcal{L}_{\text{PC}}^*$, consider $\langle *_U \rangle (\mathsf{K}_a p \wedge \widehat{\mathsf{K}}_a \widehat{\mathsf{K}}_a \neg p)$. For a contradiction, assume there is an equivalent $\alpha \in \mathcal{L}_{\text{PC}}^*$. Pick an atom q not occurring in α ; then consider symmetric and reflexive models M and M' below for $\mathbf{A} = \{a\}$.



Similarly to the first part of [Theorem 12](#), models are collectively $\mathbf{P} \setminus \{q\}$ -bisimilar, and, moreover, agent a , being the single agent in the system, does not have any communication available to her to cut any relations. At the same time, $\langle *_U \rangle (\mathsf{K}_a p \wedge \widehat{\mathsf{K}}_a \widehat{\mathsf{K}}_a \neg p)$ does not hold in pointed model (M, w) due to the fact that the first conjunct requires cutting the a -edge from w to u , and the second conjunct requires preserving the very same edge. On the other hand, since each world of M' can be uniquely defined by a Boolean formula (using atom q), we can construct an arrow update U that removes only the arrows between w'_1 and u' and preserves all other arrows. It is then straightforward to verify $(M_{U}, w'_1) \models \mathsf{K}_a p \wedge \widehat{\mathsf{K}}_a \widehat{\mathsf{K}}_a \neg p$, i.e. $(M, w'_1) \models \langle *_U \rangle (\mathsf{K}_a p \wedge \widehat{\mathsf{K}}_a \widehat{\mathsf{K}}_a \neg p)$.

For proving $\mathcal{L}_{\text{PC}}^* \not\equiv \mathcal{L}_{\text{AU}}^*$, consider the models below.



¹⁷Note: $\mathcal{L}_{\text{AU}}^*$ extends the language in [van Ditmarsch et al. \(2017\)](#) with distributed knowledge modalities.

897 Now consider the formula $\langle \{a, b\} : * \rangle D_{\{a, b\}} \perp$ in \mathcal{L}_{PC}^* . Assume that there is an
 898 equivalent formula $\alpha \in \mathcal{L}_{AU}^*$; pick an atom p not occurring in it. It is clear that
 899 $(M, w) \not\models \langle \{a, b\} : * \rangle D_{\{a, b\}} \perp$, as none of a and b can tell apart w and u . However,
 900 $(M', w_1) \models \langle \{a, b\} : * \rangle D_{\{a, b\}} \perp$ (see the highlighted partitions).

901 To see that α cannot distinguish (M, w) and (M', w_1) , first notice that because
 902 quantification in $[*_U]$ is implicit, one can use p in the arrow updates we quantify
 903 over. Thus, we can force any submodel of (M, w) using $[*_U]$. At the same time,
 904 the pairs of worlds (w_1, w_2) and (u_1, u_2) in M' are collectively bisimilar. Thus, we
 905 cannot remove an a -edge from the upper part of the model without removing
 906 the corresponding edge in the lower part. The same happens with b -edges.
 907 This, together with the fact that M and M' are collectively $P \setminus \{p\}$ -bisimilar (a
 908 witness is $\{(w, w_1), (w, w_2), (u, u_1), (u, u_2)\}$) implies that $(M, w) \models \alpha$ if and only if
 909 $(M', w_1) \models \alpha$. ■

910 5 Summary and further work

911 The focus of this paper is the action of *partial communication*. Through it, a
 912 group of agents S share, with every agent in the model, all the information they
 913 have about the truth-value of a formula χ . Semantically, this is represented
 914 by an operation through which the uncertainty of each agent is reduced by
 915 removing the uncertainty *about* χ some agent in S has already ruled out. After
 916 having recalled the basics of the framework, we showed that its language
 917 \mathcal{L}_{PC} is invariant under collective bisimulation. Moreover, we investigated
 918 the complexity of its model checking problem, proving it is in P . It has been
 919 also shown that, while the expressivity of \mathcal{L}_{PC} is exactly that of the languages
 920 for public announcements and arrow updates (all are reducible to \mathcal{L}), their
 921 update expressivity is different. Thus, all three types of communication are
 922 incomparable to each other. The focus has then shifted to a modal operator that
 923 quantifies over the topic of the communication: a setting for *arbitrary* partial
 924 communication. We have provided the operator's semantic interpretation as
 925 well as a sound and complete axiom system and invariance results for the
 926 resulting language \mathcal{L}_{PC}^* . We have also proved that the model checking problem
 927 for the new language \mathcal{L}_{PC}^* is $PSPACE$ -complete, and also showed that \mathcal{L}_{PC}^*
 928 is, expressivity-wise, incomparable to both the language for *arbitrary* public
 929 announcements and the language for *arbitrary* arrow updates.

930 The framework for partial communication provides, arguably, a natural
 931 representation of communication between agents. Indeed, it works directly
 932 with the information (i.e., uncertainty) the agents have, instead of looking for
 933 formulas that are known by the agents, and then using them as announcements
 934 (as done, e.g., when dealing with group announcements; Ågotnes et al. 2010).
 935 Additionally, the results show that this action is a truly novel epistemic action,
 936 different from others as public announcements and arrow updates.

937 There is further work to do. In the current version of the setting, some ques-
 938 tions still demand an answer. An important one is that collective bisimulation
 939 is not 'well-behaved': a model and its collective bisimulation contraction are
 940 not collectively bisimilar (Roelofsens 2005). One then wonders whether there is
 941 a more adequate notion of structural equivalence for the basic language \mathcal{L} and
 942 its extensions.

Taking into account that partial communication is incomparable, update expressivity wise, to both public announcements and arrow updates, it may be interesting to determine some special classes of pointed models where all three modalities are equivalent. Moreover, we believe that it is also worthwhile to compare partial communication to other model-changing actions, like, e.g., those of relation-changing logics (Areces et al. 2015).

Alternatively, one can expand the presented framework. For example, one can extend the languages used here by adding a *common knowledge* operator, a step that requires further technical tools (Ågotnes and Wáng 2017, Baltag and Smets 2020, Galimullin and Ågotnes 2021, Ågotnes and Galimullin 2023). Or, one can put further restrictions on communication, like costs and resource bounds (Dolgorukov and Gladyshev 2022, Dolgorukov et al. 2024).

Equally interesting is a generalisation in which the topic of conversation is rather a set of formulas, together with its connection with other forms of communication (e.g., one in which some agents share *all they know* with everybody). Yet another exciting avenue of further research is to consider private or semi-private communication within groups of agents on a given topic.

A Appendix

Proof of Theorem 4

Since \mathcal{L}_{PC} is the union of $\mathcal{L}_{PC}[n]$ for all $n \in \mathbb{N}$, the proof will proceed by induction on n . In fact, the manuscript will prove a stronger statement: for every $\psi \in \mathcal{L}_{PC}$ with $\text{at}(\psi) \subseteq Q$ and every (M, w) and (M', w') : if $(M, w) \rightleftharpoons_C^Q (M', w')$ then (1) $(M, w) \models \psi$ if and only if $(M', w') \models \psi$, and (2) $(M_{S:\psi}, w) \rightleftharpoons_C^Q (M'_{S:\psi}, w')$. So, take $M = \langle W, R, V \rangle$ and $M' = \langle W', R', V' \rangle$.

Base case. Take $\psi \in \mathcal{L}_{PC}[0] = \mathcal{L}$ with $\text{at}(\psi) \subseteq Q$; suppose $(M, w) \rightleftharpoons_C^Q (M', w')$. In this case, Item (1) is nothing but Theorem 2. For Item (2), let Z be the witness for $(M, w) \rightleftharpoons_C^Q (M', w')$; it will be shown that Z is also a collective Q -bisimulation between $M_{S:\psi} = \langle W, R^{S:\psi}, V \rangle$ and $M'_{S:\psi} = \langle W', R'^{S:\psi}, V' \rangle$. Take any $(u, u') \in Z$.

- **Atoms.** The operation does not change atomic valuations. Thus, since u and u' agree in all atoms in Q in M and M' (as Z satisfies **atoms** for those models), they also agree in such atoms in $M_{S:\psi}$ and $M'_{S:\psi}$.
- **Forth.** Take any $G \subseteq A$ and any $v \in W$ such that $R^{S:\psi}_G uv$. Since $R^{S:\psi}_G = R_{G \cup S} \cup (R_G \cap \sim_\psi^M)$ (see observation immediately after Definition 3.1), then $R_{G \cup S} uv$ or $(R_G \cap \sim_\psi^M) uv$. (i) If $R_{G \cup S} uv$ then, since Z satisfies **forth** for M and M' , there is $v' \in W'$ such that $R'_{G \cup S} u'v'$ and $(v, v') \in Z$. Since $R'^{S:\psi}_G = R'_{G \cup S} \cup (R'_G \cap \sim_\psi^{M'})$, from $R'_{G \cup S} u'v'$ it follows that $R'^{S:\psi}_G u'v'$. Thus, this $v' \in W'$ is such that $R'^{S:\psi}_G u'v'$ and $(v, v') \in Z$, as required. (ii) If $(R_G \cap \sim_\psi^M) uv$, then both $R_G uv$ and $u \sim_\psi^M v$. From the first and the fact that Z satisfies **forth** for M and M' , there is $v' \in W'$ such that $R'_G u'v'$ and $(v, v') \in Z$. Now, $u \sim_\psi^M v$ indicates that u and v agree on ψ 's truth-value. But $\psi \in \mathcal{L}$. Thus, Item (1) from this base case indicates that u and u' also agree on ψ (as $(u, u') \in Z$), and so do v and v' (from $(v, v') \in Z$). Hence, u' and v' agree on ψ 's truth-value, that is,

985 $u' \sim_{\psi}^{M'} v'$. Therefore, $(R'_G \cap \sim_{\psi}^{M'})uv$, so $R'^S: \psi_G u'v'$. This means this $v' \in W'$ is
 986 such that $R'^S: \psi_G u'v'$ and $(v, v') \in Z$, as required.

987 • **Back.** As in **forth**, using the fact that Z satisfies **back** for M and M' .

988 Thus, $M_{S: \psi} \rightleftharpoons_C^Q M'_{S: \psi}$. But $(w, w') \in Z$, so $(M_{S: \psi}, w) \rightleftharpoons_C^Q (M'_{S: \psi}, w')$.

989 **Inductive case.** Take $\psi \in \mathcal{L}_{PC}[i+1]$ with $\text{at}(\psi) \subseteq Q$; suppose $(M, w) \rightleftharpoons_C^Q (M', w')$.
 990 For **Item (1)**, proceed by structural induction on ψ . The cases for atoms, Boolean
 991 operators and D_G are as in **Theorem 2**. The remaining case is for formulas of
 992 the form $[S: \chi] \varphi$ with $\chi \in \mathcal{L}_{PC}[i]$, $\varphi \in \mathcal{L}_{PC}[i+1]$ and $\text{at}([S: \chi] \varphi) = (\text{at}(\chi) \cup$
 993 $\text{at}(\varphi)) \subseteq Q$. Here, the structural IH (the one over formulas in $\mathcal{L}_{PC}[i+1]$) states
 994 that collectively Q -bisimilar pointed models agree on the truth value of the
 995 subformula φ (as $\text{at}(\varphi) \subseteq Q$). Then, note how, since $\chi \in \mathcal{L}_{PC}[i]$, $\text{at}(\chi) \subseteq Q$ and
 996 $(M, w) \rightleftharpoons_C^Q (M', w')$, **Item (2)** of the (global) IH implies $(M_{S: \chi}, w) \rightleftharpoons_C^Q (M'_{S: \chi}, w')$.
 997 Hence, $(M_{S: \chi}, w) \models \varphi$ if and only if $(M'_{S: \chi}, w') \models \varphi$. Now, our case. From left to
 998 right, suppose $(M, w) \models [S: \chi] \varphi$. By semantic interpretation, $(M_{S: \chi}, w) \models \varphi$; thus,
 999 $(M'_{S: \chi}, w') \models \varphi$, i.e., $(M', w') \models [S: \chi] \varphi$. The right-to-left direction is analogous.

1000 It is only left to prove **Item (2)** for $\psi \in \mathcal{L}_{PC}[i+1]$ with $\text{at}(\psi) \subseteq Q$. This can be
 1001 done as in the (global) base case, using **Item (1)** from this inductive case instead.

1002 Proof of Proposition 1

It will be shown that

$$Z := \{(u, u) \in (W \times \llbracket \xi \rrbracket^M) \mid u \in \llbracket \xi \rrbracket^M\},$$

1003 is a collective bisimulation. To do so, take any $(u, u) \in Z$ (so $u \in \llbracket \xi \rrbracket^M$).

1004 • **Atoms.** Immediate: both operations use the original atomic valuation.

1005 • **Forth.** Take any $G \subseteq A$. Suppose there is $v \in W$ such that $R^\xi_G uv$; it will be
 1006 shown that v satisfies the requirements. Since $R^\xi_G uv$, every $i \in G$ is such that
 1007 $R^\xi_i uv$, that is, $R_i uv$ and $u \sim_\xi^M v$. The latter and $u \in \llbracket \xi \rrbracket^M$ imply $v \in \llbracket \xi \rrbracket^M$;
 1008 thus, $(v, v) \in Z$ and $R'_i uv$. The now latter holds for every $i \in G$, which yields
 1009 the missing piece, $R'_G uv$.

1010 • **Back.** Take any $G \subseteq A$. Suppose there is $v \in W$ such that $R'_G uv$; it will be
 1011 shown that v satisfies the requirements. Since $R'_G uv$, every $i \in G$ is such that
 1012 $R'_i uv$, that is, $R_i uv$ and $\{u, v\} \subseteq \llbracket \xi \rrbracket^M$. The latter implies not only $(v, v) \in Z$
 1013 but also $u \sim_\xi^M v$; then, $R^\xi_i uv$. The now latter holds for every $i \in G$, which
 1014 yields the missing piece, $R^\xi_G uv$.

1015 For the final detail, note how $(w, w) \in Z$ (as $w \in \llbracket \xi \rrbracket^M$).

1016 Proof of Theorem 6

1017 Since \mathcal{L}_{PA} is the union of $\mathcal{L}_{PA}[n]$ for all $n \in \mathbb{N}$, the proof will proceed by
 1018 induction on n . In fact, a stronger statement will be proved: for every $\psi \in$
 1019 \mathcal{L}_{PA} with $\text{at}(\psi) \subseteq Q$ and every (M, w) and (M', w') , if $(M, w) \rightleftharpoons_C^Q (M', w')$ then
 1020 **(1)** $(M, w) \models \psi$ if and only if $(M', w') \models \psi$, and **(2)** $(M_\psi, w) \rightleftharpoons_C^Q (M'_\psi, w')$. Thus,
 1021 take $M = \langle W, R, V \rangle$ and $M' = \langle W', R', V' \rangle$.

1022 **Base case.** Take $\psi \in \mathcal{L}_{PA}[0] = \mathcal{L}$ with $\text{at}(\psi) \subseteq Q$; suppose $(M, w) \rightleftharpoons_C^Q (M', w')$. In
 1023 this case, [Item \(1\)](#) is nothing but [Theorem 2](#). For [Item \(2\)](#), let Z be the witness
 1024 for $(M, w) \rightleftharpoons_C^Q (M', w')$; it will be shown that Z is also a collective Q -bisimulation
 1025 between $M_\psi = \langle W, R^\psi, V \rangle$ and $M'_\psi = \langle W', R'^\psi, V' \rangle$. Take any $(u, u') \in Z$.

1026 • **Atoms.** The operation does not change atomic valuations. Thus, since u
 1027 and u' agree in all atoms in Q in M and M' (as Z satisfies **atoms** for those
 1028 models), they also agree in such atoms in M_ψ and M'_ψ .

1029 • **Forth.** Take any $G \subseteq A$; suppose there is $v \in W$ such that $R^\psi_G uv$. Since
 1030 $R^\psi_G = R_G \cap \sim_\psi^M$, then $R_G uv$ and $u \sim_\psi^M v$. From the former, $(u, u') \in Z$ and
 1031 Z satisfying **forth** for M and M' , there is $v' \in W'$ such that $R'_G u'v'$ and
 1032 $(v, v') \in Z$. Now, $u \sim_\psi^M v$ says that u and v agree on ψ 's truth-value. But
 1033 $\psi \in \mathcal{L}$. Thus, [Item \(1\)](#) from this base case indicates that u and u' also agree
 1034 on ψ (from $(u, u') \in Z$), and so do v and v' (from $(v, v') \in Z$). Hence, u' and
 1035 v' agree on ψ 's truth-value, that is, $u' \sim_\psi^{M'} v'$. Thus, $R'_G u'v'$ and $u' \sim_\psi^{M'} v'$;
 1036 hence, $R'^\psi_G u'v'$, as actually required.

1037 • **Back.** As in **forth**, using the fact that Z satisfies **back** for M and M' .

1038 Thus, $M_\psi \rightleftharpoons_C^Q M'_\psi$. Moreover, $(w, w') \in Z$; thus, $(M_\psi, w) \rightleftharpoons_C^Q (M'_\psi, w')$.

1039 **Inductive case.** Take $\psi \in \mathcal{L}_{PA}[i+1]$ with $\text{at}(\psi) \subseteq Q$; suppose $(M, w) \rightleftharpoons_C^Q (M', w')$.
 1040 For [Item \(1\)](#), proceed by structural induction on ψ . The cases for atoms, Boolean
 1041 operators and D_G are as in [Theorem 2](#). The remaining case is for formulas of the
 1042 form $[\xi] \varphi$ with $\xi \in \mathcal{L}_{PA}[i]$, $\varphi \in \mathcal{L}_{PA}[i+1]$ and $\text{at}([\xi] \varphi) = (\text{at}(\xi) \cup \text{at}(\varphi)) \subseteq Q$. Now,
 1043 note how $\xi \in \mathcal{L}_{PA}[i]$ and $(M, w) \rightleftharpoons_C^Q (M', w')$ imply two facts. First, together
 1044 with [Item \(1\)](#) of the (global) IH, they imply $(M, w) \models \xi$ if and only if $(M', w') \models \xi$.
 1045 Second, together with [Item \(2\)](#) of the same, they yield $(M_\xi, w) \rightleftharpoons_C^Q (M'_\xi, w')$,
 1046 which together with the structural IH (collectively Q -bisimilar pointed models
 1047 agree on the truth value of subformulas of $[\xi] \varphi$ containing only atoms in Q),
 1048 imply $(M_\xi, w) \models \varphi$ if and only if $(M'_\xi, w') \models \varphi$ (as $\text{at}(\varphi) \subseteq Q$). Now, our case.
 1049 From left to right, suppose $(M, w) \models [\xi] \varphi$. By semantic interpretation, $(M, w) \models \xi$
 1050 implies $(M_\xi, w) \models \varphi$; thus, $(M', w') \models \xi$ implies $(M'_\xi, w') \models \varphi$, i.e., $(M', w') \models [\xi] \varphi$.
 1051 The right-to-left direction is analogous.

1052 It is only left to prove [Item \(2\)](#) for $\psi \in \mathcal{L}_{PA}[i+1]$ with $\text{at}(\psi) \subseteq Q$. This can be
 1053 done as in the (global) base case, using [Item \(1\)](#) from this inductive case instead.

1054 Proof of [Theorem 8](#)

1055 Recall the additional axiom and rule,

$$\begin{aligned} 1056 \quad A_{S,*}: & \vdash [S:*] \varphi \rightarrow [S:\chi] \varphi \quad \text{for every } \chi \in \mathcal{L}, \\ R_{S,*}: & \text{ If } \vdash \eta([S:\chi] \varphi) \text{ for all } \chi \in \mathcal{L}, \text{ then } \vdash \eta([S:*] \varphi), \end{aligned}$$

as well as the syntax for necessity forms,

$$\eta(\#) ::= \# \mid \phi \rightarrow \eta(\#) \mid D_G \eta(\#) \mid [S:\chi] \eta(\#).$$

1057 Soundness

1058 The soundness of axioms and rules on [Tables 1](#) and [2](#) has been already es-
 1059 tablished ([Theorem 1](#) and [Theorem 3](#), respectively). For those in [Table 3](#), the

1060 soundness of $A_{S,*}$ follows directly from the semantic interpretation of $[S: *]$. For
 1061 $R_{S,*}$, note first that the rule is truth-preserving. The proof of this fact relies
 1062 on the semantics of $[S: *]$, proceeding in this case by induction over necessity
 1063 forms. Take any pointed model (M, w) .

- 1064 • **Base case** ($\eta(\#) = \#$). Suppose $(M, w) \models [S: \chi] \varphi$ holds for all $\chi \in \mathcal{L}$. Then, the
 1065 semantics of $[S: *]$ imply $(M, w) \models [S: *] \varphi$.
- 1066 • **Inductive case** ($\eta(\#) = \phi \rightarrow \eta(\#)$ with $\phi \in \mathcal{L}_{PC}^*$). Suppose $(M, w) \models \phi \rightarrow$
 1067 $\eta([S: \chi] \varphi)$ holds for all $\chi \in \mathcal{L}$; suppose further that $(M, w) \models \phi$. Then,
 1068 $(M, w) \models \eta([S: \chi] \varphi)$ holds for all $\chi \in \mathcal{L}$ and hence, by IH, $(M, w) \models \eta([S: *] \varphi)$.
 1069 Thus, $(M, w) \models \phi \rightarrow \eta([S: *] \varphi)$.
- 1070 • **Inductive case** ($\eta(\#) = D_G \eta(\#)$). Suppose $(M, w) \models D_G \eta([S: \chi] \varphi)$ holds for
 1071 all $\chi \in \mathcal{L}$. By semantic interpretation, for all $u \in W$, if $R_G w u$ then $(M, u) \models$
 1072 $\eta([S: \chi] \varphi)$, for all $\chi \in \mathcal{L}$. Then, by IH, each such u is such that $(M, u) \models$
 1073 $\eta([S: *] \varphi)$; thus, $(M, w) \models D_G \eta([S: *] \varphi)$.
- 1074 • **Inductive case** ($\eta(\#) = [S: \chi] \eta(\#)$). Suppose $(M, w) \models [S': \chi'] \eta([S: \chi] \varphi)$ holds
 1075 for all $\chi \in \mathcal{L}$. By semantic interpretation, $(M_{S': \chi'}, w) \models \eta([S: \chi] \varphi)$ holds
 1076 for all $\chi \in \mathcal{L}$. Then, by IH, $(M_{S': \chi'}, w) \models \eta([S: *] \varphi)$ and therefore $(M, w) \models$
 1077 $[S': \chi'] \eta([S: *] \varphi)$.

1078 Since the rule is truth-preserving, it is also validity preserving, which completes
 1079 the proof.

1080 Completeness

1081 For completeness, the following complexity ordering will be useful.

1082 **Definition A.1** The *Boolean, dynamic and quantifier depths* of formulas in \mathcal{L}_{PC}^*
 1083 measure, respectively, the number of nested Boolean operators, communication
 1084 operators and quantifiers. They are given, respectively, by the functions δ_B , δ_Π
 1085 and δ_V , defined recursively as

$$\begin{array}{lll}
 \delta_B(p) := 1 & \delta_\Pi(p) := 0 & \delta_V(p) := 0 \\
 \delta_B(\neg\varphi) := \delta_B(\varphi) + 1 & \delta_\Pi(\neg\varphi) := \delta_\Pi(\varphi) & \delta_V(\neg\varphi) := \delta_V(\varphi) \\
 \delta_B(\varphi \wedge \psi) := \max(\delta_B(\varphi), \delta_B(\psi)) & \delta_\Pi(\varphi \wedge \psi) := \max(\delta_\Pi(\varphi), \delta_\Pi(\psi)) & \delta_V(\varphi \wedge \psi) := \max(\delta_V(\varphi), \delta_V(\psi)) \\
 \delta_B(D_G \varphi) := \delta_B(\varphi) + 1 & \delta_\Pi(D_G \varphi) := \delta_\Pi(\varphi) & \delta_V(D_G \varphi) := \delta_V(\varphi) \\
 \delta_B([S: \chi] \varphi) := (8 + \delta_B(\chi)) \delta_B(\varphi) & \delta_\Pi([S: \chi] \varphi) := \delta_\Pi(\chi) + \delta_\Pi(\varphi) + 1 & \delta_V([S: \chi] \varphi) := \delta_V(\chi) + \delta_V(\varphi) \\
 \delta_B([S: *] \varphi) := \delta_B(\varphi) & \delta_\Pi([S: *] \varphi) := \delta_\Pi(\varphi) & \delta_V([S: *] \varphi) := \delta_V(\varphi) + 1
 \end{array}$$

Then, use “ \mathcal{E} ” for a natural-language disjunction (just as “ $\&$ ” stands for a natural-language conjunction). The complexity ordering $<$ between two formulas φ, ψ in \mathcal{L}_{PC}^* gives priority to the quantifier depth, then to the dynamic depth and finally to the Boolean depth:

$$\varphi < \psi \text{ iff}_{def} \mathcal{E} \left\{ \begin{array}{l} \delta_V(\varphi) < \delta_V(\psi), \\ \delta_V(\varphi) = \delta_V(\psi) \ \& \ \delta_\Pi(\varphi) < \delta_\Pi(\psi), \\ \delta_V(\varphi) = \delta_V(\psi) \ \& \ \delta_\Pi(\varphi) = \delta_\Pi(\psi) \ \& \ \delta_B(\varphi) < \delta_B(\psi) \end{array} \right\} \blacktriangleleft$$

1087 The main ideas of this completeness proof come from the completeness
 1088 proofs for APAL (Balbiani and van Ditmarsch 2015) and epistemic logic with

distributed knowledge (Fagin et al. 1992). These ideas will be adapted and combined to prove the completeness of the stated proof system for \mathcal{L}_{PC}^* .

It is well-known that the intersection of relations is not modally definable; hence one cannot build a canonical model straight away. The strategy is, instead, to build an intermediate “pseudo-model”, where accessibility relations labelled with G are taken as primitive. This pseudo-model can be then unwind into a tree-like model, and then one can show that these structures are collectively bisimilar.

Definition A.2 A *pseudo-model* is a tuple $M = \langle W, \mathcal{R}, V \rangle$ where W and V are as in a model (Definition 2.1), and $\mathcal{R} = \{\mathcal{R}_i \subseteq W \times W \mid i \in A\} \cup \{\mathcal{R}_G \subseteq W \times W \mid G \subseteq A\}$ assigns a binary relation on W to each agent $i \in A$ and also to every group of agents $G \subseteq A$. Moreover, these relations are required to satisfy the following.

- (i) $\mathcal{R}_{\{i\}} = \mathcal{R}_i$, and
- (ii) for all $H, G \subseteq A$, if $H \subseteq G$ then $\mathcal{R}_G \subseteq \mathcal{R}_H$. ◀

The first difference between a model and a pseudo-model is that, while the first only requires relations R_i for each $i \in A$ (building the relations R_G for $G \subseteq A$ using intersections), the second requires, additionally, relations for each $G \subseteq A$. More importantly, even though the requirements in a pseudo-model guarantee that $\mathcal{R}_G \subseteq \bigcap_{i \in G} \mathcal{R}_i$, the subset relation in the other direction might not hold: one can have pairs that are in \mathcal{R}_i for every $i \in G$ without being in \mathcal{R}_G . This is the main difference w.r.t. models where, by definition, $\bigcap_{i \in G} R_i = R_G$. In fact, while every model is a pseudo-model, not every pseudo-model is a model. Still, note how formulas in \mathcal{L}_{PC}^* can be interpreted in pseudo-models in the same way they are semantically interpreted in models.

While the construction of the canonical model usually requires maximal consistent sets of formulas, the strategy here uses the somewhat different maximal consistent *theories*. Recall that the derivation system under discussion consists of the axioms and rules on Tables 1, 2 and 3.

Definition A.3 Let \mathcal{APC} be the minimal set that contains all the instances of the derivation system’s axiom schemata and is closed under all its rules. A set $x \subseteq \mathcal{L}_{PC}^*$ is called a *theory* if and only if (T1) $\mathcal{APC} \subseteq x$, (T2) x is closed under MP (Table 1) and (T3) x is closed under $R_{S;*}$ (Table 3).

A theory x is *consistent* if and only if there is no $\varphi \in \mathcal{L}_{PC}^*$ such that $\varphi \in x$ and $\neg\varphi \in x$. A theory x is *maximal* if and only if either $\varphi \in x$ or $\neg\varphi \in x$ for all $\varphi \in \mathcal{L}_{PC}^*$. The smallest theory is \mathcal{APC} , and the largest theory is \mathcal{L}_{PC}^* . ◀

Note: while theories are required to be closed under MP and $R_{S;*}$, they are not required to be closed under the two other rules of the system, G_D and $RE_{S;\chi}$. This is because, while MP and $R_{S;*}$ preserve both validity and truth, G_D and $RE_{S;\chi}$ rules preserve validity but not truth.

The following theories will be of great help during the proof.

Lemma 1 Let x be a theory; take $\varphi, \chi \in \mathcal{L}_{PC}^*$. Then, all of the following are theories.

1130 (i) $\phi \rightarrow x := \{\xi \mid \phi \rightarrow \xi \in x\}$, 1132 (iii) $[S:\chi]x := \{\xi \mid [S:\chi]\xi \in x\}$

1131 (ii) $D_G x := \{\xi \mid D_G \xi \in x\}$,

1133 *Proof.*

1134 (i) (T1) Take any $\xi \in \mathcal{APC}$. By propositional reasoning, $\phi \rightarrow \xi \in \mathcal{APC}$ for any
1135 $\phi \in \mathcal{L}_{PC}^*$; in particular, $\phi \rightarrow \xi \in \mathcal{APC}$. Since x is a theory, $\mathcal{APC} \subseteq x$, so
1136 $\phi \rightarrow \xi \in x$. Hence, by definition, $\xi \in \phi \rightarrow x$.

1137 (T2) Take $\phi \rightarrow \xi$ and ϕ in $\phi \rightarrow x$; then, $\phi \rightarrow (\phi \rightarrow \xi)$ and $\phi \rightarrow \phi$ are in x .
1138 Being a propositional validity, $(\phi \rightarrow (\phi \rightarrow \xi)) \rightarrow ((\phi \rightarrow \phi) \rightarrow (\phi \rightarrow \xi))$
1139 is in \mathcal{APC} , and thus it is also in x (as x is a theory). But, being a theory,
1140 x is closed under MP, so $(\phi \rightarrow \phi) \rightarrow (\phi \rightarrow \xi)$ is in x , and thus so is
1141 $\phi \rightarrow \xi$. Hence, by definition, $\xi \in \phi \rightarrow x$.

1142 (T3) Suppose $\eta([S:\chi]\psi) \in \phi \rightarrow x$ for every $\chi \in \mathcal{L}$; then, $\phi \rightarrow \eta([S:\chi]\psi) \in x$
1143 for every $\chi \in \mathcal{L}$. Being a theory, x is closed under $R_{S,*}$; moreover,
1144 $\phi \rightarrow \eta(\#)$ is a necessity form. Hence, $\phi \rightarrow \eta([S:*]\psi) \in x$ and thus, by
1145 definition, $\eta([S:*]\psi) \in \phi \rightarrow x$.

1146 (ii) (T1) Take any $\xi \in \mathcal{APC}$. From G_D it follows that $D_G \xi \in \mathcal{APC}$; but x is a
1147 theory, so $\mathcal{APC} \subseteq x$ and hence $D_G \xi \in x$. Thus, by definition, $\xi \in D_G x$.

1148 (T2) Take $\phi \rightarrow \xi$ and ϕ in $D_G x$; then, $D_G(\phi \rightarrow \xi)$ and $D_G \phi$ are in x . From
1149 axiom K_D we have $D_G(\phi \rightarrow \xi) \rightarrow (D_G \phi \rightarrow D_G \xi) \in \mathcal{APC}$ and thus
1150 $D_G(\phi \rightarrow \xi) \rightarrow (D_G \phi \rightarrow D_G \xi) \in x$. But, being a theory, x is closed
1151 under MP, so $D_G \phi \rightarrow D_G \xi \in x$ and then $D_G \xi \in x$. Hence, by definition
1152 $\xi \in D_G x$.

1153 (T3) Suppose $\eta([S:\chi]\phi) \in D_G x$ for every $\chi \in \mathcal{L}$; then, $D_G \eta([S:\chi]\phi) \in x$ for
1154 every $\chi \in \mathcal{L}$. Being a theory, x is closed under $R_{S,*}$; moreover, $D_G \eta(\#)$
1155 is a necessity form. Hence, $D_G \eta([S:*]\phi) \in x$ and thus, by definition,
1156 $\eta([S:*]\phi) \in D_G x$.

1157 (iii) (T1) Take any $\xi \in \mathcal{APC}$. The rule

1158 $\text{if } \vdash \phi \text{ then } \vdash [S:\chi]\phi$

1159 is derivable in the system for any S and χ ,¹⁸ so $[S:\chi]\xi \in \mathcal{APC}$. But
1160 x is a theory, so $\mathcal{APC} \subseteq x$ and hence $[S:\chi]\xi \in x$. Thus, by definition,
1161 $\xi \in [S:\chi]x$.

1162 (T2) Take $\phi \rightarrow \xi$ and ϕ in $[S:\chi]x$. Then, both $[S:\chi](\phi \rightarrow \xi)$ and $[S:\chi]\phi$ are
1163 in x . The axiom

1164 $\vdash [S:\chi](\phi \rightarrow \xi) \rightarrow ([S:\chi]\phi \rightarrow [S:\chi]\xi)$

¹⁸Suppose $\vdash \phi$. From $\vdash \neg(\neg p \wedge p)$, propositional reasoning yields $\vdash \phi \leftrightarrow \neg(\neg p \wedge p)$ for any atom p . Then, $RE_{S,\chi}$ produces the first piece, $\vdash [S:\chi]\phi \leftrightarrow [S:\chi]\neg(\neg p \wedge p)$. For the second piece, axiom $A_{S,\chi}^-$ yields $\vdash [S:\chi]\neg(\neg p \wedge p) \leftrightarrow \neg[S:\chi](\neg p \wedge p)$ and axiom $A_{S,\chi}^+$ yields $\vdash [S:\chi](\neg p \wedge p) \leftrightarrow ([S:\chi]\neg p \wedge [S:\chi]p)$, so $\vdash \neg[S:\chi](\neg p \wedge p) \leftrightarrow \neg([S:\chi]\neg p \wedge [S:\chi]p)$. From those two, propositional reasoning yields $\vdash [S:\chi]\neg(\neg p \wedge p) \leftrightarrow \neg([S:\chi]\neg p \wedge [S:\chi]p)$. For the third piece, axiom $A_{S,\chi}^-$ yields $\vdash [S:\chi]\neg p \leftrightarrow \neg[S:\chi]p$. Then, propositional reasoning produces $\vdash ([S:\chi]\neg p \wedge [S:\chi]p) \leftrightarrow (\neg[S:\chi]p \wedge [S:\chi]p)$, from which $\vdash \neg([S:\chi]\neg p \wedge [S:\chi]p) \leftrightarrow \neg(\neg[S:\chi]p \wedge [S:\chi]p)$ follows. From the three pieces and propositional reasoning, one gets $\vdash [S:\chi]\phi \leftrightarrow \neg(\neg[S:\chi]p \wedge [S:\chi]p)$. But the right-hand side of this equivalence is a tautology. Then, by propositional reasoning, $\vdash [S:\chi]\phi$.

1165 is derivable in the system,¹⁹ so it is in \mathcal{APC} and thus also in x . But,
 1166 being a theory, x is closed under MP, so $[S:\chi]\phi \rightarrow [S:\chi]\xi \in x$ and then
 1167 $[S:\chi]\xi \in x$. Hence, by definition $\xi \in [S:\chi]x$.
 1168 (T3) Suppose $\eta([S':\chi']\phi) \in [S:\chi]x$ for every $\chi' \in \mathcal{L}$; then, $[S:\chi]\eta([S':\chi']\psi) \in$
 1169 x for every $\chi' \in \mathcal{L}$. Being a theory, x is closed under $R_{S,*}$; moreover,
 1170 $[S:\chi]\eta(\#)$ is a necessity form. Hence, $[S:\chi]\eta([S':*]\phi) \in x$ and thus, by
 1171 definition, $\eta([S':*]\phi) \in [S:\chi]x$. ■

1172 Here are two further useful properties of theories that can be proven simi-
 1173 larly to, e.g., Lemma 8 and Proposition 15 of Galimullin 2021.

1174 **Lemma 2** *If x is a theory, then $\varphi \in \varphi \rightarrow x$ and $x \subseteq \varphi \rightarrow x$.* ■

1175 **Lemma 3** *Let φ be a formula and x be a theory. Then $\varphi \rightarrow x$ is consistent if and only*
 1176 *if $\neg\varphi \notin x$.* ■

1177 Theories share some properties with maximal consistent sets.

1178 **Lemma 4** *Every consistent theory can be extended to a maximal consistent one.*

1179 *Proof.* Let x be a consistent theory; let $\{\psi_0, \psi_1, \dots\}$ be an enumeration of the
 1180 \mathcal{L}_{PC}^* -formulas. The maximal consistent theory y is built inductively. First, take
 1181 $y_0 := x$. Then, given a consistent theory y_n satisfying $x \subseteq y_n$, consider the n th
 1182 formula of the enumeration, ψ_n .

- 1183 • If $\neg\psi_n \notin y_n$, then define $y_{n+1} := y_n \rightarrow \psi_n$.
- 1184 • If $\neg\psi_n \in y_n$, consider two cases.
 - 1185 – if $\neg\psi_n$ is not of the form $\neg\eta([S:*]\phi)$, then define $y_{n+1} := y_n$.
 - 1186 – if $\neg\psi_n$ is of the form $\neg\eta([S:*]\phi)$, then define $y_{n+1} := \neg\eta([S:\chi]\phi) \rightarrow y_n$,
 1187 with $\neg\eta([S:\chi]\phi)$ being the first formula in the enumeration that is not in
 1188 y_n .

1189 From its definition, y_{n+1} is a theory such that $y_n \subseteq y_{n+1}$ (Lemma 2). From its
 1190 construction and Lemma 3, it is consistent.

1191 Now, take $y := \bigcup_{n \in \mathbb{N}} y_n$. Its consistency follows from the consistency of all
 1192 y_n . Moreover: it is a theory as it satisfies (T1), (T2) and (T3). The first follows
 1193 because $x \subseteq y$ and x is a theory. The second is straightforward. For the third,
 1194 consider its two cases.

- 1195 • If $\neg\eta([S:*]\phi) \notin y_n$, then $\eta([S:*]\phi) \in y_{n+1}$ and therefore $\eta([S:*]\phi) \in y$. But
 1196 $\mathcal{APC} \subset y$ so, by axiom $A_{S,*}$ and closure under MP, it follows that $\eta([S:\chi]\phi) \in$
 1197 y for all $\chi \in \mathcal{L}$.
- 1198 • If $\neg\eta([S:*]\phi) \in y_n$ then, by construction, there is a χ such that $\neg\eta([S:\chi]\phi) \in$
 1199 y_{n+1} . so $\neg\eta([S:\chi]\phi) \in y$. Then, by y 's consistency, $\eta([S:\chi]\phi) \notin y$.

¹⁹In fact, the equivalence is derivable. By propositional reasoning, $\vdash (\varphi \rightarrow \psi) \leftrightarrow \neg(\varphi \wedge \neg\psi)$, so rule $RE_{S,\chi}$ yields $\vdash [S:\chi](\varphi \rightarrow \psi) \leftrightarrow [S:\chi]\neg(\varphi \wedge \neg\psi)$. From axiom $A_{S,\chi}^-$ one gets $\vdash [S:\chi]\neg(\varphi \wedge \neg\psi) \leftrightarrow \neg[S:\chi](\varphi \wedge \neg\psi)$. From axiom $A_{S,\chi}^+$ one gets $\vdash [S:\chi](\varphi \wedge \neg\psi) \leftrightarrow ([S:\chi]\varphi \wedge [S:\chi]\neg\psi)$ and thus, by propositional reasoning, $\vdash \neg[S:\chi](\varphi \wedge \neg\psi) \leftrightarrow \neg([S:\chi]\varphi \wedge [S:\chi]\neg\psi)$. Axiom $A_{S,\chi}^-$ also produces $\vdash [S:\chi]\neg\psi \leftrightarrow \neg[S:\chi]\psi$, which via propositional reasoning can be turned into $\vdash ([S:\chi]\varphi \wedge [S:\chi]\neg\psi) \leftrightarrow ([S:\chi]\varphi \wedge \neg[S:\chi]\psi)$ and then into $\vdash \neg([S:\chi]\varphi \wedge [S:\chi]\neg\psi) \leftrightarrow \neg([S:\chi]\varphi \wedge \neg[S:\chi]\psi)$. Finally, propositional reasoning also produces $\vdash \neg([S:\chi]\varphi \wedge \neg[S:\chi]\psi) \leftrightarrow ([S:\chi]\varphi \rightarrow [S:\chi]\psi)$. From the five pieces and propositional reasoning, one gets $\vdash [S:\chi](\varphi \rightarrow \psi) \leftrightarrow ([S:\chi]\varphi \rightarrow [S:\chi]\psi)$.

1200 It is only left to show that y is maximal. Take any ψ_n in the enumeration.
 1201 If $\neg\psi_n \notin y_n$ then, by construction, $\psi_n \in y_{n+1}$ (Lemma 2) and thus $\psi_n \in y$.
 1202 Otherwise, $\neg\psi_n \in y_n$ so $\neg\psi_n \in y$. ■

1203 One can now define the canonical pseudo-model.

1204 **Definition A.4** The canonical pseudo-model \mathbb{M} is the tuple $\langle \mathbb{W}, \mathbb{R}, \mathbb{V} \rangle$ where

$$\begin{aligned} \mathbb{W} &:= \{x \mid x \text{ is a maximal consistent theory}\}, \\ \mathbb{R}_G &:= \{(x, y) \subseteq \mathbb{W} \times \mathbb{W} \mid D_H x \subseteq y \text{ for all } \emptyset \subset H \subseteq G\}, \\ 1205 \quad \mathbb{V}(p) &:= \{x \in \mathbb{W} \mid p \in x\}. \end{aligned} \quad \blacktriangleleft$$

1206 The following lemma plays the role of the existence lemma.

1207 **Lemma 5** Let x be a theory. If $D_G \varphi \notin x$, then there is a maximal consistent theory y
 1208 such that $D_G x \subseteq y$ and $\varphi \notin y$.

1209 *Proof.* Suppose $D_G \varphi \notin x$. By definition, $\varphi \notin D_G x$, so $\neg\varphi \rightarrow D_G x$ is a consistent
 1210 theory (Lemma 3); by Lemma 4, it can be extended into a maximal consistent
 1211 theory y containing $\neg\varphi$. Then, from its consistency, y does not contain φ . ■

1212 Finally, the truth lemma.

Lemma 6 For every $\phi \in \mathcal{L}_{PG}^*$ and every maximal consistent theory x ,

$$(\mathbb{M}, x) \models \phi \quad \text{if and only if} \quad \phi \in x$$

1213 *Proof.* The proof proceeds by structural induction on ϕ .

1214 • **Base case** p . By the definition of the valuation, as $x \in \mathbb{V}(p)$ iff $p \in x$.

1215 For the inductive cases, the IH states that $(\mathbb{M}, x) \models \psi$ iff $\psi \in x$ holds for all
 1216 maximal consistent theories x and formulas ψ such that $\psi < \phi$.

1217 • **Inductive cases** $\neg\varphi, \varphi \wedge \psi$. Straightforward.

1218 • **Inductive case** $D_G \varphi$. (\Rightarrow) For a contraposition argument, suppose $D_G \varphi \notin x$.
 1219 Then, by Lemma 5, there is a $y \in \mathbb{W}$ such that both $D_G x \subseteq y$ and $\varphi \notin y$. By
 1220 the definition of \mathbb{R}_G and IH, this means that there is a $y \in \mathbb{W}$ such that both
 1221 $\mathbb{R}_G xy$ and $(\mathbb{M}, y) \not\models \varphi$. Therefore, by semantic interpretation, $(\mathbb{M}, x) \not\models D_G \varphi$.
 1222 (\Leftarrow) Suppose $D_G \varphi \in x$; take any $y \in \mathbb{W}$ such that $\mathbb{R}_G xy$. From $D_G \varphi \in x$ it
 1223 follows that $\varphi \in D_G x$; from $\mathbb{R}_G xy$ it follows that $D_G x \subseteq y$. From these two
 1224 pieces, $\varphi \in y$; thus, by IH, $(\mathbb{M}, y) \models \varphi$. So, every $y \in \mathbb{W}$ with $\mathbb{R}_G xy$ is such
 1225 that $(\mathbb{M}, y) \models \varphi$; hence, $(\mathbb{M}, x) \models D_G \varphi$.

1226 • **Inductive cases** $[S: \chi]p, [S: \chi]\neg\varphi, [S: \chi](\varphi \wedge \psi), [S: \chi]D_G \varphi$ and $[S: \chi][S': \chi']\varphi$.
 1227 They are all handled using the axioms and rule in Table 2 (see Velázquez-
 1228 Quesada 2022 for a similar proof detailing how they are used). Here, just
 1229 the case for $[S: \chi]D_G \varphi$ is (briefly) discussed. From the soundness of axiom
 1230 $A_{S: \chi}^D$, it follows that $(\mathbb{M}, x) \models [S: \chi]D_G \varphi$ if and only if $(\mathbb{M}, x) \models D_{SUG} [S: \chi]\varphi \wedge$
 1231 $D_G^x [S: \chi]\varphi$. But the complexity among the formulas inside the scope of
 1232 $[S: \chi]$ has decreased, so $D_{SUG} [S: \chi]\varphi \wedge D_G^x [S: \chi]\varphi < [S: \chi]D_G \varphi$; thus, by IH,
 1233 $D_{SUG} [S: \chi]\varphi \wedge D_G^x [S: \chi]\varphi \in x$. Now, x is a theory, so it contains \mathcal{APC} and
 1234 thus, in particular, it contains (all instances of) axiom $A_{S: \chi}^D$ and is closed
 1235 under MP. Hence, $D_{SUG} [S: \chi]\varphi \wedge D_G^x [S: \chi]\varphi \in x$ if and only if $[S: \chi]D_G \varphi \in x$.

- 1236 • **Inductive case** $[S: \chi][S': *]\varphi$. (\Rightarrow) Suppose $(\mathbb{M}, x) \Vdash [S: \chi][S': *]\varphi$, so $(\mathbb{M}, x) \Vdash$
1237 $[S: \chi][S': \chi']\varphi$ for all $\chi' \in \mathcal{L}$. But $[S: \chi][S': \chi']\varphi < [S: \chi][S': *]\varphi$; hence, from
1238 IH, it follows that $[S: \chi][S': \chi']\varphi \in x$, for all $\chi' \in \mathcal{L}$. Now, $[S: \chi]\eta(\#)$ is a
1239 necessity form; since x is closed under rule $R_{S: *}$, it follows that $[S: \chi][S': *]\varphi \in$
1240 x . (\Leftarrow) Suppose $[S: \chi][S': *]\varphi \in x$. Since x is a theory, $[S: \chi][S': \chi']\varphi \in x$,
1241 for all $\chi' \in \mathcal{L}$. Once again, $[S: \chi][S': \chi']\varphi < [S: \chi][S': *]\varphi$, so from IH it
1242 follows that $(\mathbb{M}, x) \Vdash [S: \chi][S': \chi']\varphi$ holds for all $\chi' \in \mathcal{L}$, that is, $(\mathbb{M}_{S: \chi}, x) \Vdash$
1243 $[S': \chi']\varphi$ holds for all $\chi' \in \mathcal{L}$. By semantic interpretation, this is equivalent
1244 to $(\mathbb{M}_{S: \chi}, x) \Vdash [S': *]\varphi$, and thus to $(\mathbb{M}, x) \Vdash [S: \chi][S': *]\varphi$.
- 1245 • **Inductive case** $[S: *]\varphi$. (\Rightarrow) Suppose $(\mathbb{M}, x) \Vdash [S: *]\varphi$. Then, $(\mathbb{M}, x) \Vdash [S: \chi]\varphi$
1246 for all $\chi \in \mathcal{L}$. But $[S: \chi]\varphi < [S: *]\varphi$ so, from IH, $[S: \chi]\varphi \in x$ for all $\chi \in \mathcal{L}$.
1247 Since x is closed under rule $R_{S: *}$, it follows that $[S': *]\varphi \in x$. (\Leftarrow) Suppose
1248 $[S': *]\varphi \in x$. From axiom $A_{S: *}$ and x 's closure under MP we have $[S: \chi]\varphi \in x$
1249 for all $\chi \in \mathcal{L}$. But $[S: \chi]\varphi < [S: *]\varphi$ so, from IH, $(\mathbb{M}, x) \Vdash [S: \chi]\varphi$ for all $\chi \in \mathcal{L}$.
1250 Thus, $(\mathbb{M}, x) \Vdash [S: *]\varphi$. ■

1251 With the canonical pseudo-model \mathbb{M} satisfying this truth lemma, the final
1252 stage of the proof consists in creating a collectively bisimilar structure (so it
1253 agrees with \mathbb{M} in the satisfiability of formulas in \mathcal{L}_{PC}^*) that is, additionally, a
1254 *model*. The new structure is a tree-like model \mathbb{M} obtained by unravelling \mathbb{M}
1255 around every world in its domain \mathbb{W} . As a result, \mathbb{M} has a forest structure with
1256 no unique root.

1257 **Definition A.5** The tree-like canonical model \mathbb{M} is the tuple $\langle \mathbb{W}, R, V \rangle$ where

- 1258 • \mathbb{W} is the set of all finite paths $\mathbf{x} = \langle x_0 \cdot G_1 \cdot x_1 \cdot \dots \cdot G_n \cdot x_n \rangle$ such that x_k is in \mathbb{W} for
1259 every $[0 .. n]$ and $R_{G_{k+1}}x_kx_{k+1}$ for every $k \in [0 .. n - 1]$. The last world in a path
1260 \mathbf{x} is denoted as $\text{last}(\mathbf{x})$.
- 1261 • $R = \{R_i \subseteq \mathbb{W} \times \mathbb{W} \mid i \in A\}$ with $R_i := \{(\mathbf{x}, \mathbf{y}) \mid \mathbf{y} = \langle \mathbf{x} \cdot G \cdot \text{last}(\mathbf{y}) \rangle \text{ and } i \in G\}$. Write
1262 R_G for $\bigcap_{i \in G} R_i$.
- 1263 • For all $p \in P$, $V(p) := \{\mathbf{x} \in \mathbb{W} \mid p \in \text{last}(\mathbf{x})\}$. ◀

1264 Note how \mathbb{M} is a model. More importantly: concerning the satisfiability of
1265 formulas in \mathcal{L}_{PC}^* , it is just as \mathbb{M} . Since every model is a pseudo-model, the
1266 following lemma will treat \mathbb{M} and \mathbb{M} as pseudo-models.

1267 **Lemma 7** The structures $\mathbb{M} = \langle \mathbb{W}, R, V \rangle$ and $\mathbb{M} = \langle \mathbb{W}, \mathbb{R}, \mathbb{V} \rangle$ are collectively bisimilar.

Proof. Define the following relation, connecting each theory $x \in \mathbb{W}$ with every
path in \mathbb{W} whose last world is x :

$$Z = \{(x, \mathbf{x}) \mid x = \text{last}(\mathbf{x})\}.$$

1268 To show that Z is a collective bisimulation, take any $(x, \mathbf{x}) \in Z$.

- 1269 • **Atoms.** For every atom p we have $x \in V(p)$ iff $p \in x$ (definition of V) iff
1270 $p \in \text{last}(\mathbf{x})$ (as $x = \text{last}(\mathbf{x})$, by definition of Z) iff $\mathbf{x} \in V(p)$ (definition of V).
- 1271 • **Forth.** Take any $G \subseteq A$ and any $y \in \mathbb{W}$ such that R_Gxy . Because of $x = \text{last}(\mathbf{x})$
1272 and R_Gxy , the path \mathbf{x} can be extended into the path $\mathbf{y} = \langle \mathbf{x} \cdot G \cdot y \rangle$; since y is
1273 the last world in this path, we actually have $\mathbf{y} = \langle \mathbf{x} \cdot G \cdot \text{last}(\mathbf{y}) \rangle$. From the
1274 definition of R , it follows that R_Gxy . Finally, we have $y = \text{last}(\mathbf{y})$, so $(y, \mathbf{y}) \in Z$.

1275 • **Back.** Take any $G \subseteq A$ and any $y \in W$ such that $R_G xy$. From the definition of
 1276 R , it follows that $y = \langle x \cdot G \cdot y \rangle$ for some world y . Then, by the definition of a
 1277 path, $R_G \text{last}(x)y$. Finally, it is clear that $y = \text{last}(y)$, so $(y, y) \in Z$.
 1278 It is only left to show that Z is non-empty, for which it is enough to notice
 1279 that every theory $x \in W$ has a matching path $x = \langle x \rangle$, which clearly satisfies
 1280 $\text{last}(x) = x$. ■

1281 Finally, for completeness, one argues that every valid formula is derivable
 1282 in the system, which is equivalent to saying that every valid formula is in \mathcal{APC} .

1283 **Theorem 14** Every valid formula in \mathcal{L}_{PC}^* is in \mathcal{APC} .

1284 *Proof.* For a contradiction, suppose there is a valid φ such that $\varphi \notin \mathcal{APC}$. Build
 1285 the theory $\neg\varphi \rightarrow \mathcal{APC}$ which, by Lemma 3, is consistent and, by Lemma 2,
 1286 contains $\neg\varphi$. Then, by Lemma 4, $\neg\varphi \rightarrow \mathcal{APC}$ can be extended into a maximal
 1287 consistent theory x such that $\neg\varphi \rightarrow \mathcal{APC} \subseteq x$. Moreover: since x is consistent
 1288 and it contains $\neg\varphi$, we have $\varphi \notin x$. But then, $(M, x) \not\models \varphi$ (by Lemma 6) and thus
 1289 $(M, \langle x \rangle) \not\models \varphi$ (from Lemma 7 and Theorem 9). Hence, φ is false in some model,
 1290 contradicting the fact that it is valid. ■

1291 Proof of Theorem 9

1292 Since \mathcal{L}_{PC}^* is the union of $\mathcal{L}_{PC}^*[n]$ for all $n \in \mathbb{N}$, proceed again by induction on n
 1293 (as in the proof of Theorem 4). Again, one proves a stronger statement: for every
 1294 $\psi \in \mathcal{L}_{PC}^*$ with $\text{at}(\psi) \subseteq Q$ and every (M, w) and (M', w') , if $(M, w) \rightleftharpoons_C^Q (M', w')$
 1295 then (1) $(M, w) \models \psi$ if and only if $(M', w') \models \psi$, and (2) $(M_{S:\psi}, w) \rightleftharpoons_C^Q (M'_{S:\psi}, w')$.
 1296 Thus, take $M = \langle W, R, V \rangle$ and $M' = \langle W', R', V' \rangle$.

1297 **Base case.** This base case is for formulas in $\mathcal{L}_{PC}^*[0]$, defined as the basic language
 1298 \mathcal{L} plus the modality $[S: *]$. For Item (1), proceed by structural induction. The
 1299 cases for formulas in \mathcal{L} (atoms, Boolean operators and D_G) are covered by
 1300 Theorem 2. For the remaining case, take $[S: *]\varphi$ with $\varphi \in \mathcal{L}$ and $\text{at}([S: *]\varphi) =$
 1301 $\text{at}(\varphi) \subseteq Q$; suppose $(M, w) \rightleftharpoons_C^Q (M', w')$. From left to right, if $(M, w) \models [S: *]\varphi$
 1302 then, by semantic interpretation, $(M_{S:\chi}, w) \models \varphi$ holds for every $\chi \in \mathcal{L}$. But from
 1303 $(M, w) \rightleftharpoons_C^Q (M', w')$ and the fact each χ is in \mathcal{L} , it follows that $(M_{S:\chi}, w) \rightleftharpoons_C^Q$
 1304 $(M'_{S:\chi}, w')$ for every $\chi \in \mathcal{L}$ (essentially Item (2) in the base case of the proof
 1305 of Theorem 4, as the proof also works for any χ , regardless of the atoms it
 1306 contains). Then, from IH and $\text{at}(\varphi) \subseteq Q$, it follows that $(M'_{S:\chi}, w') \models \varphi$ for every
 1307 $\chi \in \mathcal{L}$; hence, $(M', w') \models [S: *]\varphi$. The right-to-left direction is analogous. For
 1308 Item (2), proceed as in the same case in the proof of Theorem 4, using now the
 1309 just proved Item (1) for formulas in $\mathcal{L}_{PC}^*[0]$.

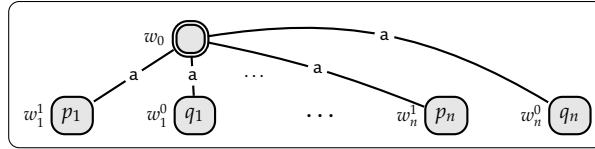
1310 **Inductive case.** As in the same case in the proof of Theorem 4.

1311 Proof of Theorem 11

1312 Constructing restrictions takes polynomial time (due to polynomial time con-
 1313 struction of the bisimulation contraction; see, e.g., Kanellakis and Smolka 1990)
 1314 and thus polynomial space. The space required for the $[S: \chi]\psi$ case is bounded
 1315 by $O(|\varphi| \cdot |M|)$. For the $[S: *]\psi$ case, collective bisimulation contraction can be

1316 computed in polynomial time and space, and each restriction has a size of at
 1317 most $|M|$. If one traverses a given formula depth-first and reuses memory, the
 1318 space to store model restrictions is polynomial in $|\varphi|$ (even though the algorithm
 1319 itself runs in exponential time). Thus, the space required for the case of $[S: *] \psi$
 1320 is bounded by $O(|\varphi| \cdot |M|)$. Finally, since computing each subformula of φ re-
 1321 quires space bounded by $O(|\varphi| \cdot |M|)$, the space required by the whole algorithm
 1322 is bounded by $O(|\varphi|^2 \cdot |M|)$. The algorithm follows closely the semantics of \mathcal{L}_{PC}^* ,
 1323 and correctness can be shown via induction on φ . For the case of quantifiers
 1324 note that, to switch from bipartitions to particular formulas corresponding to
 1325 those partitions, one can use characteristic formulas (van Ditmarsch et al. 2014),
 1326 which are built in such a way that they are true only in one world of a model
 1327 (up to collective bisimilarity).

1328 To show that the model checking problem is *PSPACE*-hard, use the classic
 1329 reduction from the satisfiability of QBF. Without loss of generality, consider
 1330 QBFs without free variables in which every variable is quantified only once.
 1331 Consider a QBF with n variables $\{x_1, \dots, x_n\}$. We need a formula in \mathcal{L}_{PC}^* and
 1332 a model with the size of both being polynomial on the size of the QBF. The
 1333 (reflexive and symmetric) model M^n below satisfies this: w_0 is the evaluation
 1334 point, and for each variable x_i there are two worlds, w_i^1 and w_i^0 , corresponding
 1335 respectively to evaluating x_i to 1 and to 0. Assume that each w_i^1 satisfies only p_i
 1336 and each w_i^0 satisfies only q_i . Observe that R_b is just the identity.



1337

Let $\Psi := Q_1 x_1 \dots Q_n x_n \Phi(x_1, \dots, x_n)$ be a quantified Boolean formula (so $Q_i \in \{\forall, \exists\}$ and $\Phi(x_1, \dots, x_n)$ is Boolean). The formula $chosen_k$ below indicates, intuitively, that the values (either 1 or 0) of the first k variables have been chosen (thus, for $1 \leq i \leq k$, exactly one world in $\{w_i^1, w_i^0\}$ can be accessed from w).

$$chosen_k := \bigwedge_{1 \leq i \leq k} (\widehat{K}_a p_i \leftrightarrow \neg \widehat{K}_a q_i) \wedge \bigwedge_{k < i \leq n} (\widehat{K}_a p_i \wedge \widehat{K}_a q_i).$$

Here is, then, a recursive translation from Ψ to a formula ψ in \mathcal{L}_{PC}^* :

$$\begin{aligned} \psi_0 &:= \Phi(\widehat{K}_a p_1, \dots, \widehat{K}_a p_n), \\ \psi_k &:= \begin{cases} [a, b : *](chosen_k \rightarrow \psi_{k-1}) & \text{if } Q_k = \forall \\ \langle [a, b : *](chosen_k \wedge \psi_{k-1}) \rangle & \text{if } Q_k = \exists \end{cases} , \\ \psi &:= \psi_n. \end{aligned}$$

1338 Now, we need to show that

1339 $Q_1 x_1 \dots Q_n x_n \Phi(x_1, \dots, x_n)$ is satisfiable if and only if $(M^n, w_0) \models \psi$.

1340 For this, observe that each world in M^n can be characterised by a unique
 1341 formula. Moreover, relation b is the identity. Therefore, $[a, b : *]$ and $\langle [a, b : *] \rangle$
 1342 can force any restriction of the a -edges from w_0 to w_i 's. In the model, worlds

1343 w_i^1 and w_i^0 correspond to the truth-value of x_i . The guard $chosen_k$ guarantees
 1344 that only the truth-values of the first k variables have been chosen, and that
 1345 they have been chosen unambiguously (i.e. there is exactly one edge from w_0
 1346 to either w_i^1 and w_i^0). Thus, together with $[\{a, b\} : *]$ and $\langle \{a, b\} : * \rangle$, the guards
 1347 $chosen_k$ emulate \forall and \exists . Then, once the values of all x_i 's have been set, the
 1348 evaluation of the QBF corresponds to the a-reachability of the corresponding
 1349 worlds in M^n .

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