Dynamic Epistemic Logic of Resource Bounded Information Mining Agents

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Motivation

Reasoning about resource-bounded agents has drawn the attention of various MAS researchers recently and brings us closer to modelling real-life situations.

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- Different epistemic logics treat resources as various constraints on agents' rationality: non-omniscient agents, reasoners who take time to derive consequences of their knowledge, DEL-style logics with inferential actions that require spending resources, etc.
- Logics of strategic abilities, in which agents' actions are associated with costs. And thus state-to-state transitions require spending some resources.

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Examples include medical tests, scientific experiments, database queries, etc.

Other Modelling Choices

• The cost of the same formula may be different for different agents and it can also be different across different states. Thus, the agent may be unaware of the cost of some formula for herself and for other agents as well.

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- The budget of each agent may also be different in different states, agents may be unaware of their own and others' budgets.

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Language

Let $\mathbb{AG} = \{a_1, \dots, a_k\}$ be a finite set of agents. We fix a set of terms

$$\mathsf{Terms} = \{ c_{(A,i)} \mid A \in \mathcal{L}_{PL}, i \in \mathbb{AG} \} \cup \{ b_i \mid i \in \mathbb{AG} \}$$

Syntax

$$\varphi ::= p \mid (z_1 t_1 + \cdots + z_n t_n) \geq z) \mid \neg \varphi \mid (\varphi \land \varphi) \mid K_i \varphi \mid C_G \varphi \mid [?^A_G] \varphi,$$

where $p \in \text{Prop}$, $t_1, \ldots, t_n \in \text{Terms}$, $z_1, \ldots, z_n, z \in \mathbb{Z}^a$, $i \in \mathbb{AG}$, $G \subseteq \mathbb{AG}$, and $A \in \mathcal{L}_{PL}$.

^aA formula of the form $t \ge \frac{1}{2}$ can be viewed as an abbreviation for $2t \ge 1$, so we allow rational numbers to appear in our syntax.

We interpret the dynamic operator $[?_G^A]\varphi$ as "after a group query by G whether formula A is true, φ is true". Or, alternatively, "if G performs query A, they can achieve φ ".

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- K_a(b_i + b_j) ≥ c_i(p ∨ q) for "agent a knows that the joint budget of i and j is higher than the cost of p ∨ q for agent i",
- $[?_G^{(p\vee q)}]C_H\psi$ meaning that "after a joint query about $p \vee q$ by G it is common knowledge among H that ψ ".

Models

A model is a tuple $\mathcal{M} = (W, (\sim_i)_{i \in \mathbb{AG}}, \text{ Cost}, \text{ Bdg}, V)$, where

- W is a non-empty set of *states*,
- $\sim_i \subseteq (W \times W)$ is an equivalence relation for each $i \in \mathbb{AG}$,
- Cost: $\mathbb{AG} \times W \times \mathcal{L}_{PL} \longrightarrow \mathbb{Q}^+ \cup \{0\}$ assigns the (non-negative) *cost* to propositional formulas for each agent in each state, s.t.
 - $\operatorname{Cost}_i(w, \top) = 0$,
 - $A \approx B \Rightarrow \text{Cost}_i(w, A) = \text{Cost}_i(w, B)$, where $A \approx B$ iff $A \equiv B$ or $A \equiv \neg B$.
- Bdg: $\mathbb{AG} \times W \longrightarrow \mathbb{Q}^+ \cup \{0\}$ is the (non-negative) *bugdet* of each agent at each state,
- $V: \operatorname{Prop} \longrightarrow 2^W$ is a *valuation* of propositional variables.

Single-agent Case

Example

Alice needs test herself for COVID. It normally costs 20 resources and Alice has only 10. Luckily, she has a premium membership with 50% discount. But another agent Billy does not know about it (though he knows about the membership discount).

$$b_{a} = 10$$

$$p, c_{a}(p) = 10 \quad \neg p, c_{a}(p) = 10 \qquad p, b_{a} = 0 \qquad p, b_{a} = 0$$

$$\underbrace{w_{1}}_{a, b, w_{3}} \qquad \underbrace{w_{1}}_{a, b, w_{4}} \qquad \underbrace{w_{2}}_{a, b, w_{4}} \qquad$$

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Updated Model

Given a model \mathcal{M} , an agent $i \in \mathbb{AG}$ and a formula $A \in \mathcal{L}_{PL}$, an *updated* model \mathcal{M}' is a tuple $\mathcal{M}' = (W', (\sim'_i)_{i \in \mathbb{AG}}, \operatorname{Cost}', \operatorname{Bdg}', V')$, where

•
$$W' = \{w \in W \mid \mathcal{M}, w \models b_i \ge c_i(A)\};$$

• $\sim'_j = (W' \times W') \cap \sim^*_j$ with

$$\sim_j^* = \begin{cases} \sim_j & \text{if } j \neq i, \\ \sim_j \bigcap \left(([A]_{\mathcal{M}} \times [A]_{\mathcal{M}}) \bigcup ([\neg A]_{\mathcal{M}} \times [\neg A]_{\mathcal{M}}) \right) & \text{if } j = i; \end{cases}$$

•
$$\operatorname{Cost}_{j}^{\prime}(w, B) = \operatorname{Cost}_{j}(w, B)$$
, for all $B \in \mathcal{L}_{PL}, j \in \mathbb{AG}$;
• $\operatorname{Bdg}_{j}^{\prime}(w) = \begin{cases} \operatorname{Bdg}_{j}(w) - c_{i}(A), & \text{if } j = i, \\ \operatorname{Bdg}_{j}(w), & \text{if } j \neq i, \end{cases}$
• $V^{\prime}(p) = V(p) \cap W^{\prime}$ for all $p \in \operatorname{Prop.}$

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From single agents to groups

Since the access to the information is non-symmetric (different costs for different agents), it may be rational for agents to cooperate and optimize the amount of resources they need to obtain certain information.

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Group queries are performed by the following procedure: identify $i \in G$ with the lowest cost of A, let each member of G transfer $\frac{Cost_i(w,A)}{|G|}$ resources to i, then let i ask whether A is true and tell the answer to all agents in G.

Example

Telescope example

Three countries n, m and l are seeking to know a certain fact p about the universe. If any of them build a very expensive telescope, it will give them a correct answer. Country n is the richest among others having 15 abstract resources $(b_n = 15)$. But due to some reasons, e.g. higher labour costs, it requires the highest amount of resources $c_n(p) = 30$ to build a telescope there. Country m has only 10 resources $(b_m = 10)$, but it can build a telescope for $c_m(p) = 20$, for example due to better logistics. Country *I* is the poorest country with only $b_l = 5$ resources, while the cost of a telescope is the same as for n, so $c_l(p) = 30$. Finally, we assume that the costs of the telescope are known to all agents, *n* and *m* know the budgets of each other as well as I's budget. But I is unaware of the exact budget of *m*: it considers both options $b_m = 10$ and $b_m = 9$ as possible ones.

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Example



Formulas $b_n = 15$, $b_l = 5$, $c_n(p) = 30$, $c_m(p) = 20$ and $c_l(p) = 30$ hold in all four states of \mathcal{M} .

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Example

$$p, b_{m} = 10 \qquad p, b_{m} = 9 \qquad p, b_{m} = 0$$

$$\underbrace{w_{1}}_{I} \qquad I \qquad w_{3} \qquad \underbrace{w_{1}}_{I} \qquad \underbrace{w_{1}}_{I} \qquad \underbrace{w_{2}}_{I} \qquad \underbrace{w_{2$$

Formulas $b_n = 15$, $b_l = 5$, $c_n(p) = 30$, $c_m(p) = 20$ and $c_l(p) = 30$ hold in all four states of \mathcal{M} .

After the update, formulas $b_l = 5$, $c_n(p) = 30$, $c_m(p) = 20$ and $c_l(p) = 30$ hold in both w_1 and w_2 as before. But $b_n = 15$ no longer holds, since *n*'s budget is decreased after update: $b_n - \frac{c_m(p)}{|\{n,m\}|} = 5$

Some Syntactic Sugar

Let's abbreviate *"the Budget Constraint of agent i* \in *G for the G's query A*" as

$$\mathsf{BC}_i(G,A) \equiv \frac{\min_{j \in G}(c_j(A))}{|G|}$$

Then, denote the fact that *"the Budget Constraint for the query A for G is Satisfied"* as

$$BCS(G,A) \equiv \bigwedge_{i \in G} (b_i \ge \mathbf{BC}_i(G,A))$$

If BCS(G, A) holds, we say that the query $[?_G^A]$ is realisable. Note that BCS(G, A) is in fact a formula of SPQ:

$$\mathsf{BCS}(G,A) \equiv \bigvee_{j \in G} \left(\bigwedge_{i \in G} \left(c_j(A) \le c_i(A) \land b_i \ge \frac{c_j(A)}{|G|} \right) \right)$$

Updated Model

Given a model \mathcal{M} , a group $G \subseteq \mathbb{AG}$ and a formula $A \in \mathcal{L}_{PL}$, an *updated* model \mathcal{M}' is a tuple $\mathcal{M}' = (W', (\sim'_i)_{i \in \mathbb{AG}}, \operatorname{Cost}', \operatorname{Bdg}', V')$, where

•
$$W' = \{w \in W \mid \mathcal{M}, w \vDash \mathsf{BCS}(G, A)\};$$

•
$$\sim'_j = (W' imes W') \cap \sim^*_j$$
 with

$$\sim_j^* = \begin{cases} \sim_j & \text{if } j \notin G, \\ \sim_j \bigcap \left(([A]_{\mathcal{M}} \times [A]_{\mathcal{M}}) \bigcup ([\neg A]_{\mathcal{M}} \times [\neg A]_{\mathcal{M}}) \right) & \text{if } j \in G; \end{cases}$$

•
$$\operatorname{Cost}_{j}'(w, B) = \operatorname{Cost}_{j}(w, B)$$
, for all $B \in \mathcal{L}_{PL}, j \in \mathbb{AG}$;
• $\operatorname{Bdg}_{j}'(w) = \begin{cases} \operatorname{Bdg}_{j}(w) - \frac{\min \operatorname{Cost}_{i}(w, A)}{|G|}, & \text{if } j \in G, \\ \operatorname{Bdg}_{j}(w), & \text{if } j \notin G, \end{cases}$
• $V'(p) = V(p) \cap W'$ for all $p \in \operatorname{Prop}$.

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Theorem 1.

SPQ is complete.

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Reduction-style axioms (except
$$C_G \varphi$$
):
(r_ρ) [? $_G^A$] $p \leftrightarrow (BCS(G, A) \rightarrow p)$
(r_{\geq}) [? $_G^A$] $(\sum_{i=1}^k a_i t_i \geq z) \leftrightarrow (BCS(G, A) \rightarrow (\sum_{i=1}^k a_i t_i \geq z)^{(G,A)})$
(r_{\neg}) [? $_G^A$] $\neg \varphi \leftrightarrow BCS(G, A) \rightarrow \neg$ [? $_G^A$] φ
(r_{\wedge}) [? $_G^A$] $(\varphi \wedge \psi) \leftrightarrow$ [? $_G^A$] $\varphi \wedge$ [? $_G^A$] ψ
(r_{κ_1) [? $_G^A$] $K_j \varphi \leftrightarrow BCS(G, A) \rightarrow K_j$ [? $_G^A$] φ , for $j \notin G$
(r_{κ_2) [? $_G^A$] $K_i \varphi \leftrightarrow BCS(G, A) \rightarrow \bigwedge_{A' \in \{A, \neg A\}} ((A' \rightarrow K_i(A' \rightarrow [?_G^A]\varphi))),$
 $i \in G$
(RC2) from $\chi \rightarrow$ [? $_G^A$] ψ and ($\chi \wedge BCS(G, A)$) \rightarrow
 $\rightarrow \bigwedge_{A' \in \{A, \neg A\}} (A' \rightarrow E_{H \cap G}(A' \rightarrow \chi)) \wedge E_{H \setminus G} \chi$, infer $\chi \rightarrow$ [? $_G^A$] $C_H \psi$

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Theorem 2.

SAT problem for SPQ is decidable.

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Theorem 3.

Model checking SPQ is in P.

MC algorithm mimics the definitions of semantics.

• One can add axioms like (A1) $(b_i = k) \rightarrow K_i(b_i = k)$ and (A2) $(c_i(A) = k) \rightarrow K_i(c_i(A) = k)$

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- Costs can be represented as vectors (r_1, \ldots, r_k) , where each $r_l \in (r_1, \ldots, r_k)$ represents a specific resource

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- Costs can be represented as vectors (r_1, \ldots, r_k) , where each $r_l \in (r_1, \ldots, r_k)$ represents a specific resource
- How much should composed formulas cost?
- Future work: Quantified queries

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